

# Dual-mode control magnetically-coupled energy storage inductor boost inverter for renewable energy

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**Abstract:** A novel magnetically-coupled energy storage inductor boost inverter circuit for renewable energy and the dual-mode control strategy with instantaneous value feedback of output voltage are proposed. In-depth research and analysis on the circuit, control strategy, voltage transmission characteristics, etc., providing the parameter design method of magnetically-coupled energy storage inductors and output filter. The circuit topology is cascaded by the input source  $V_{in}$ , the input filter  $C_{in}$ , a single-phase inverter bridge with a magnetically-coupled energy storage inductor, and a  $CL$  filter; The control strategy serves the output voltage as a reference to achieve the switch of step-down and step-up modes smoothly. The simulation results of a 1000 VA 100–200 VDC, 220 V 50 Hz AC inverter show that the proposed inverter can realize single-stage boost power conversion, which can adapt to resistive, capacitive and inductive loads, has high power density and low output waveform distortion. It has good application prospects in small and medium-capacity single-phase inverter occasions with low input voltage.

**Key words:** inter-harmonic, parameter identification, power system, synchrosqueezed transform, time-frequency analysis

## 1. Introduction

With the increasing tension around the use of major energy sources like oil, coal and natural gas, special attention is being paid to the development and utilization of new energy sources. The DC-AC inverter has a wide range of applications where DC power is converted from other new



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energy sources such as DC generators, batteries, solar cells, fuel cells, and wind power [1–7]. From the perspective of circuit topology, it is usually divided into the boost inverter, buck inverter, and buck-boost inverter. The buck inverter has the characteristics of step-down, low reliability when the load is short-circuited and large output capacity [8, 9]. The boost inverter has the characteristics of step-up, high reliability when the load is short-circuited and has large output capacity [10–12]. The buck-boost inverter has the ability of buck-boost, high reliability when the load is short-circuited and has small output capacity.

In the case of low input voltage, the boost capability of inverters is demanding. The boost inverter has the following three types of schemes:

1. The traditional low-frequency link (LFL) buck circuit structure, such as a full-bridge, half-bridge and push-pull inverter, whose output terminal is connected to a step-up power frequency transformer. It has the characteristics of high conversion efficiency, large capacity, large noise, high cost and electrical isolation between input and output [13].
2. High-frequency link (HFL) circuit structure, such as a two-stage HFL inverter composed of a DC converter and SPWM inverter bridge, a quasi-single-stage HFL inverter cascaded with a DC converter and polarity reversal inverter bridge, an HFL inverter composed of two identical bidirectional DC choppers in differential form, which has the features of high conversion efficiency, small capacity and low weight, but high cost [14–16].
3. Non-isolated inverse circuit structure, such as the combined boost and buck-boost DC converter type circuit structure, consisting of two non-isolated bidirectional DC converters that output inverted low-frequency (LF) sinusoidal pulsating DC voltage in parallel with the input terminals and the output terminals in reverse series. The structure has the defect regarding the current circulating between two DC converters, unsatisfactory conversion efficiency and a large number of components [17, 19]. Single-stage Z-source and quasi-Z-source inverter circuit structure, with high output waveform quality, high reliability and impedance, but the capacity and weight are relatively large [20, 21].

In order to overcome the shortcomings of the above-mentioned boost inverter scheme, this paper proposes a dual-mode control magnetically-coupled energy storage inductor boost inverter. The inverter connects the two coils of the inductor in series on the two inverter bridge arms. During the step-up mode, a single coil can realize the magnetization and demagnetization of the core independently, which satisfies the working principle of the boost converter. In the step-down mode, two coils are required to work alternately, respectively responsible for the magnetization and demagnetization of the core, to meet the magnetic balance of the circuit. The paper presents research on the topology of the inverter, control strategy, voltage transmission characteristics, coupled energy storage inductor, filter parameter design and other key issues, finally, gives the results of circuit simulation.

## 2. Circuit topology and mode of magnetically-coupled energy storage inductor boost inverter

### 2.1. Circuit topology

The circuit topology of a magnetically-coupled energy storage inductor boost inverter is shown in Fig. 1. The circuit is composed of the cascaded input source  $V_{in}$ , the input filter  $C_{in}$ , a single-phase inverter bridge with a magnetically-coupled energy storage inductor, and a  $CL$

filter. This single-phase inverter bridge consists of magnetically-coupled energy storage inductors and 4 four-quadrant power switches. Among them, the coupled inductance  $L_1 = L_2 = L$ , and the four-quadrant power switch is composed of two MOSFET in reverse series which has the ability to withstand bidirectional voltage stress and bidirectional current stress. The inverter achieves the inversion and the two-way power flow by adjusting the combination of the corresponding duty cycle and the switching states of the inverter.

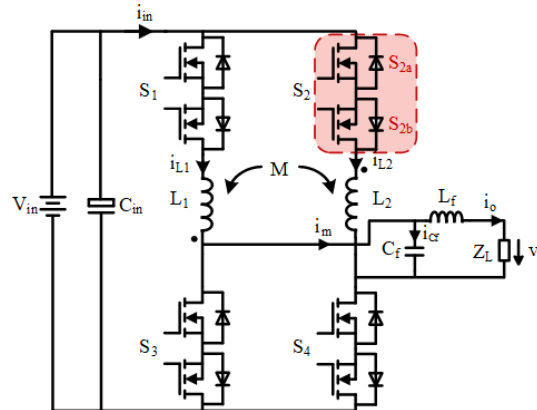


Fig. 1. Magnetically-coupled energy storage inductor boost inverter circuit topology

## 2.2. Circuit mode

For the coupled inductors  $L_1$  and  $L_2$ , it may be assumed that the magnetic core is in a positive magnetization state when the inductor current  $i_{L1}$  increases, and the magnetic core is in a negative magnetization state (positive demagnetization) when  $i_{L2}$  increases. The proposed inverter has four circuit modes:  $L_1$  magnetization mode with positive core magnetization,  $L_2$  magnetization mode with negative core magnetization,  $L_1$  feeding mode, and  $L_2$  feeding mode.

The  $L_1$  magnetization mode is shown in Fig. 2(a). At this time, the switches  $S_{1a}$ ,  $S_{1b}$ ,  $S_{3a}$ , and  $S_{3b}$  are turned on, and the magnetic core is in positive magnetization by  $V_{in}$  through the left bridge arm and  $L_1$ . The load is supplied by the output filter.

The  $L_2$  magnetization mode is shown in Fig. 2(b). At this time, the switches  $S_{1a}$ ,  $S_{1b}$ ,  $S_{4a}$ , and  $S_{4b}$  are turned on, and the magnetic core is in negative magnetization by  $V_{in}$  through the right bridge arm and  $L_2$ . The load is supplied by the output filter.

The  $L_1$  feeding mode is shown in Fig. 2(c). At this time, the switches  $S_{2a}$ ,  $S_{2b}$ ,  $S_{4a}$ , and  $S_{4b}$  are turned on.  $V_{in}$  and  $L_1$  provide energy to the load through the inverter bridge. When  $V_{in} < v_o$ , the magnetic core is in positive demagnetization. When  $V_{in} > v_o$ , the magnetic core is in positive magnetization.

The  $L_2$  feeding mode is shown in Fig. 2(d). At this time, the switches  $S_{2a}$ ,  $S_{2b}$ ,  $S_{3a}$ , and  $S_{3b}$  are turned on.  $V_{in}$  and  $L_2$  provide energy to the load through the inverter bridge. When  $V_{in} < -v_o$ , the magnetic core is in negative demagnetization; when  $V_{in} > -v_o$ , the magnetic core is in the negative magnetization.

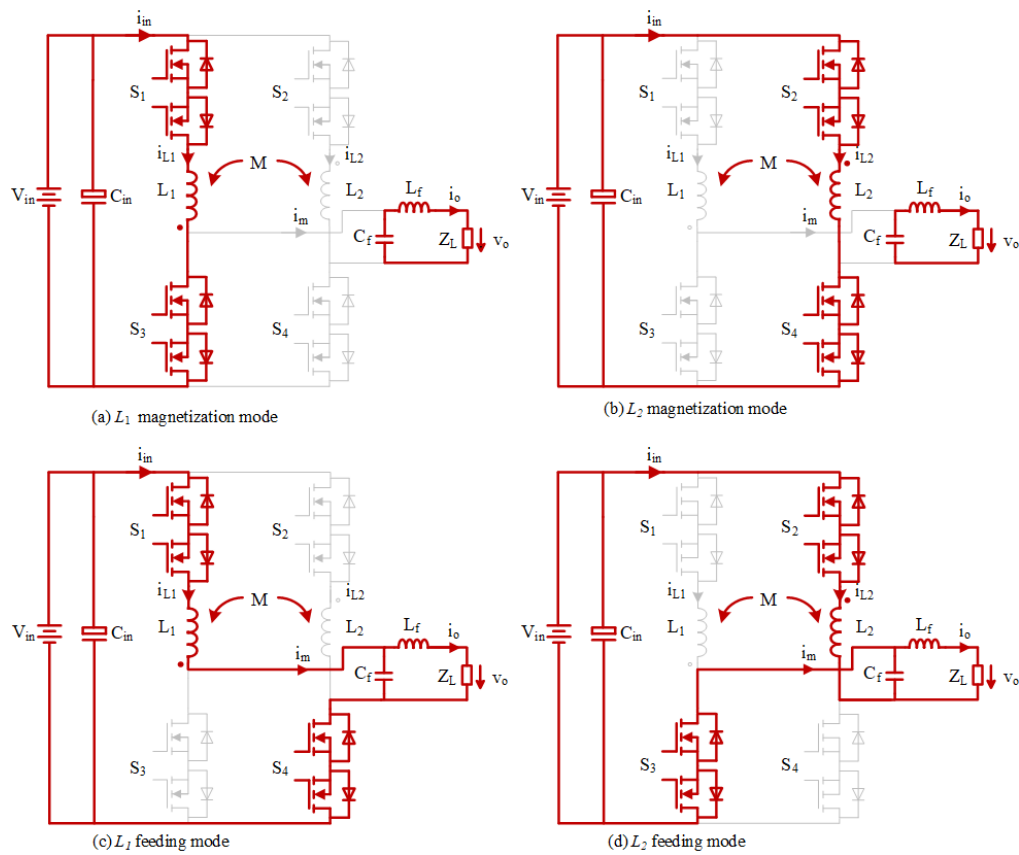


Fig. 2. Modal diagram of magnetically-coupled energy storage inductor boost inverter:  $L_1$  magnetization mode (a);  $L_2$  magnetization mode (b);  $L_1$  feeding mode (c);  $L_2$  feeding mode (d)

### 3. Operating mode and control strategy of magnetically-coupled energy storage inductor boost inverter

#### 3.1. Operating mode

According to the feature of the four circuit modes, considering the magnetic balance of the core, the operating mode of the inverter in an LF output cycle can be divided into step-up mode and step-down mode.

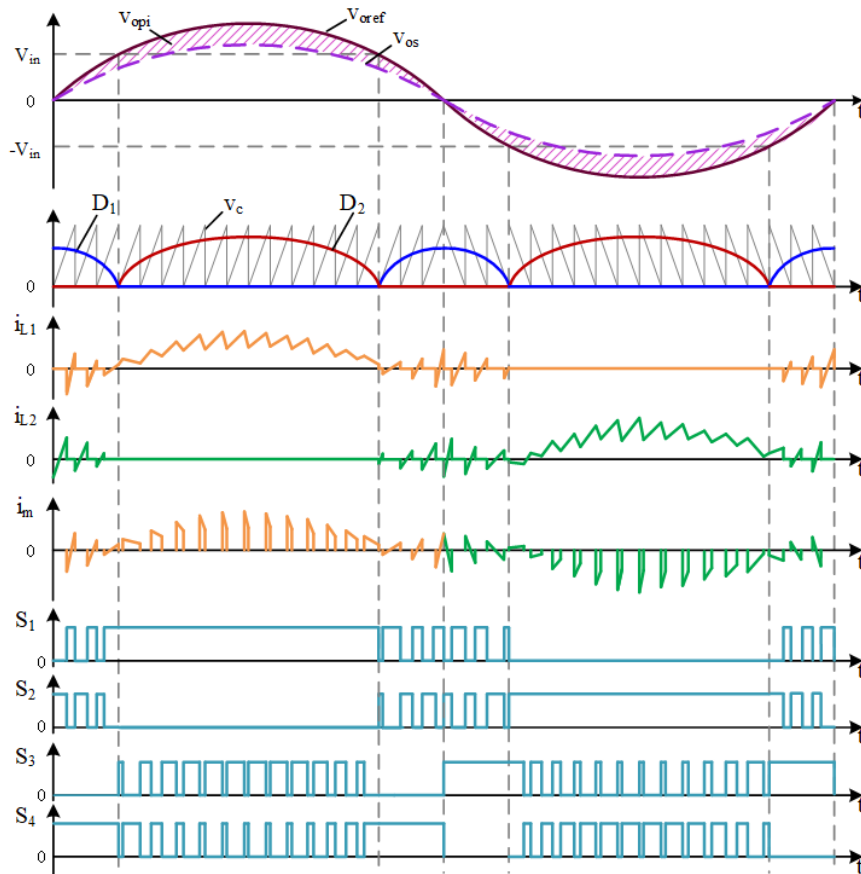
When  $V_{in} > |v_o|$ , the inverter works in step-down mode. Each high-frequency (HF) switching period  $T_s$  of this mode includes  $L_2(L_1)$  magnetization mode in the period of  $D_1 T_s$  and  $L_1(L_2)$  feeding mode in the period of  $(1 - D_1 - D_2) T_s$  ( $D_2 = 0$  in step-down mode). If  $v_o > 0$ ,  $L_2$  and  $L_1$  work in magnetization mode and feeding mode, respectively; if  $v_o < 0$ ,  $L_1$  and  $L_2$  work in magnetization mode and feeding mode, respectively.  $L_1$  and  $L_2$  work alternately in each  $T_s$  of this mode.

When  $V_{in} < |v_o|$ , the inverter works in step-up mode. Each HF switching period  $T_s$  of this mode includes  $L_1(L_2)$  magnetization mode in the period of  $D_2T_s$  and  $L_1(L_2)$  feeding mode in the period of  $(1 - D_1 - D_2)T_s$  ( $D_1 = 0$  in step-up mode). If  $v_o > 0$ , only  $L_1$  works; if  $v_o < 0$ , only  $L_2$  works.

It can be seen that the positive half-cycle of  $v_o$  has  $L_1$  magnetization mode,  $L_2$  magnetization mode and  $L_1$  feeding mode, where the  $L_1$  feeding mode appears in each  $T_s$ ; Similarly, the negative half-cycle of  $v_o$  has  $L_1$  magnetization mode, the  $L_2$  magnetization mode and the  $L_2$  feed mode, where the  $L_2$  feed mode appears in each  $T_s$ .

### 3.2. Dual mode control strategy

The magnetically-coupled energy storage inductor boost inverter adopts the step-up and step-down dual-mode control strategy with instantaneous value feedback of output voltage, and the strategy is shown in Fig. 3. In step-down mode,  $S_1$  and  $S_2$  work in complementary conduction at HF while  $S_3$  and  $S_4$  work in complementary conduction at LF in positive and negative half cycle of  $v_o$ .  $D_2$  is 0 and  $D_1$  decreases as  $v_o$  rises. The inductor current  $i_{L1}$  and  $i_{L2}$  are complementary



(a)

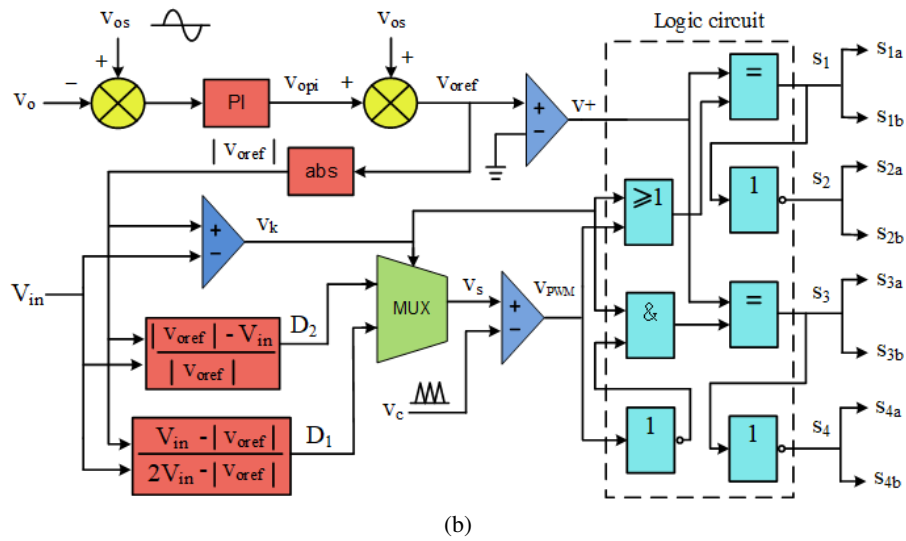


Fig. 3. Dual-mode control strategy based on instantaneous value feedback of output voltage: control principle waveform (a); control block diagram (b)

intermittently. The modulation current  $i_m$  is equal to the inductor current; In step-up mode,  $S_1$  and  $S_2$  work in complementary conduction at LF while  $S_3$  and  $S_4$  work in complementary conduction at HF in positive and negative half-cycle of the output voltage.  $D_1 = 0$  and  $D_2$  increases as  $v_o$  rises. The coupled inductors  $L_1$ ,  $L_2$  conduct at LF in positive and negative half-cycles of the output voltage,  $i_m$  is equal to the feeding inductor current. In addition, the polarity of  $v_{oref}$  is served as the basis of output positive and negative half-cycle voltages. In Fig. 3,  $v_{os}$  is the output voltage reference value,  $v_{oref}$  is the calculation reference value,  $v_+$  is the output waveform polarity judgment signal,  $v_k$  is the step-up or step-down mode signal, and  $v_{PWM}$  is the feed signal. Table 1 shows the relationship between the control signal and the power switch drive signal in the control block diagram.

Table 1. The relationship between control signal and power switch drive signal of inverter

$v_+$	$v_k$	$v_{PWM}$	$S_1$	$S_2$	$S_3$	$S_4$
1	1	1	1	0	0	1
1	1	0	1	0	1	0
1	0	1	1	0	0	1
1	0	0	0	1	0	1
0	1	1	0	1	1	0
0	1	0	0	1	0	1
0	0	1	0	1	1	0
0	0	0	1	0	1	0

#### 4. Voltage transmission characteristics of magnetically-coupled energy storage inductor boost inverter

The circuit modes of the magnetically-coupled energy storage inductor boost inverter are symmetrical in the positive and negative half-cycles of the output voltage, and there are three circuit modes in each half cycle. The equivalent circuits of these three circuit modes in the positive half-cycle are shown in Fig. 4.

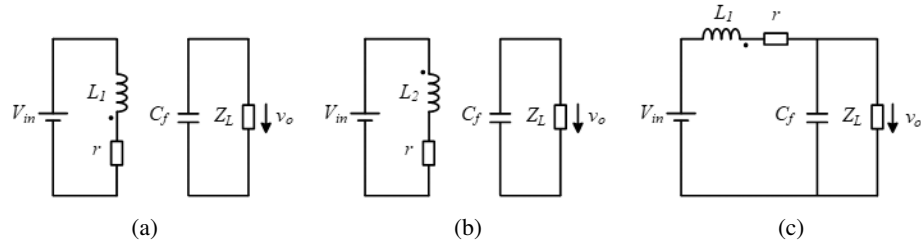


Fig. 4. Circuit modal equivalent circuit diagram:  $L_1$  magnetization equivalent mode (a);  $L_2$  magnetization equivalent mode (b);  $L_1$  feeding equivalent mode (c)

The state equation of  $L_1$  magnetization mode is:

$$\begin{cases} N \frac{d\varphi}{dt} + \frac{\varphi}{L} r = V_{in} \\ C_f \frac{dv_o}{dt} + \frac{v_o}{R_L} = 0 \end{cases} \quad (1)$$

The state equation of  $L_2$  magnetization mode is:

$$\begin{cases} N \frac{d\varphi}{dt} + \frac{\varphi}{L} r = -V_{in} \\ C_f \frac{dv_o}{dt} + \frac{v_o}{R_L} = 0 \end{cases} \quad (2)$$

The state equation of  $L_1$  feeding mode is:

$$\begin{cases} N \frac{d\varphi}{dt} + \frac{\varphi}{L} r = V_{in} - v_o \\ C_f \frac{dv_o}{dt} + \frac{v_o}{R_L} = \frac{\varphi}{L} \end{cases} \quad (3)$$

In the formula:  $\varphi$  is the magnetic flux of magnetic core;  $N$  is the number of coil turns of  $L_1$  and  $L_2$ ;  $r$  is the equivalent resistance including the inductor winding, the power switch and the diode on-state resistance.

According to the conservation of magnetic flux and the average value of  $v_o$  during a high HF cycle, the voltage transfer ratio  $M$  can be obtained as:

$$M = \frac{(1 - 2D_1)(1 - D_1 - D_2)R_L}{r + (1 - D_1 - D_2)^2 R_L} \quad (4)$$

It can be seen from Eq. (4) that the voltage range theoretically depends on the maximum voltage transfer ratio  $M_{\max}$  of the inverter in the step-mode ( $D_1 = 0$ ). If the set resistance is  $r = 0.25 \Omega$  and load  $R_L = 48.4 \Omega$ , then the maximum voltage transfer ratio is 6.95 when  $D_2 = 0.928$ . Considering the utilization rate of the step-up mode, the maximum range of  $D_2$  is limited to 0.40 to 0.70, and the range of  $M_{\max}$  is 1.64 to 3.15. When  $V_m = 311 \text{ V}$ , the output voltage range of the proposed inverter is about 100 V to 200 V.

Suppose that

$$v_{\text{oref}} = V_m \sin(\omega_0 t + \theta_0), \quad \theta_1 = \arcsin \frac{V_{\text{in}}}{V_m}, \quad k = 0, 1, 2, 3, \dots$$

When neglecting the resistance  $r$ , the inductor magnetizing duty ratios  $D_1(t)$  and  $D_2(t)$  are:

$$D_1(t) = \begin{cases} \frac{V_{\text{in}} - |V_m \sin(\omega_0 t + \theta_0)|}{2V_{\text{in}} - |V_m \sin(\omega_0 t + \theta_0)|} & t \in \left( k\pi, k\pi + \frac{\theta_1 - \theta_0}{\omega_0} \right) \cup \left( k\pi + \pi - \frac{\theta_1 - \theta_0}{\omega_0}, k\pi + \pi \right) \\ 0 & t \in \left( k\pi + \frac{\theta_1 - \theta_0}{\omega_0}, k\pi + \pi - \frac{\theta_1 - \theta_0}{\omega_0} \right) \end{cases}, \quad (5)$$

$$D_2(t) = \begin{cases} 0 & t \in \left( k\pi, k\pi + \frac{\theta_1 - \theta_0}{\omega_0} \right) \cup \left( k\pi + \pi - \frac{\theta_1 - \theta_0}{\omega_0}, k\pi + \pi \right) \\ \frac{|V_m \sin(\omega_0 t + \theta_0)| - V_{\text{in}}}{|V_m \sin(\omega_0 t + \theta_0)|} & t \in \left( k\pi + \frac{\theta_1 - \theta_0}{\omega_0}, k\pi + \pi - \frac{\theta_1 - \theta_0}{\omega_0} \right) \end{cases}. \quad (6)$$

Eqs. (5) and (6) indicate that  $D_1 = 0$  in the step-up mode and  $D_2 = 0$  in the step-down mode.

### 5. Design of coupled energy storage inductor

For the step-down mode, taking the positive half-cycle of the output voltage as an instance, the waveforms of the coupled inductor currents  $i_{L1}$ ,  $i_{L2}$  and the core magnetic flux  $\varphi$  in an HF switching period are shown in Fig. 5. In the duration of  $(0, D_1 T_s)$ , the circuit works in the  $L_2$  magnetization mode. The core is magnetized in the negative direction and the inductor current

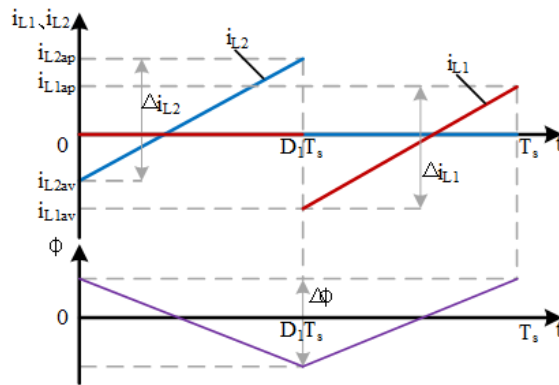


Fig. 5. The change of high-frequency period inductor current and magnetic core flux



$i_{L1} = 0$ ,  $i_{L2}$  rises; In the duration of  $(D_1 T_s, T_s)$ , the circuit works in the  $L_1$  feeding mode, the core is magnetized in the positive direction, the inductor current  $i_{L1}$  rises,  $i_{L2} = 0$ .

In an HF cycle, the variation of the currents  $\Delta i_{L1}$  and  $\Delta i_{L2}$  are respectively:

$$\Delta i_{L1} = \Delta i_{L2} = \frac{D_1 \cdot T_s \cdot V_{in}}{L}. \quad (7)$$

According to the magnetic potential balance, the peak and valley values of  $i_{L1}$  and  $i_{L2}$  have the following relationship:

$$i_{L2av} = -i_{L1ap}, \quad (8)$$

$$i_{L2ap} = -i_{L1av}. \quad (9)$$

The average value of the input current  $I_{in}$  in an HF cycle:

$$I_{in} = (1 - 2D_1) \cdot \left[ i_{L1av} + \frac{D_1 \cdot T_s \cdot V_{in}}{2L} \right]. \quad (10)$$

It can be obtained from the conservation of power:

$$I_{in} = \frac{v_o i_o}{V_{in}}. \quad (11)$$

Through Formulas (5), (10) and (11), the peak and valley values  $i_{L1ap}$  and  $i_{L1av}$  of the inductor current in an HF cycle in the step-down mode can be obtained:

$$i_{L1ap} = p_o \cdot \frac{2V_{in} - v_o}{v_o \cdot V_{in}} + \frac{T_s \cdot V_{in} \cdot (V_{in} - v_o)}{2L \cdot (2V_{in} - v_o)}, \quad (12)$$

$$i_{L1av} = p_o \cdot \frac{2V_{in} - v_o}{v_o \cdot V_{in}} - \frac{T_s \cdot V_{in} \cdot (V_{in} - v_o)}{2L \cdot (2V_{in} - v_o)}. \quad (13)$$

The inverter in the step-up mode is equivalent to the operating state of the boost converter. Taking the output positive half-cycle as an example, the peak value, valley value  $i_{L1bp}$  and  $i_{L1bv}$  of the inductor current in an HF switching cycle are respectively:

$$i_{L1bp} = \frac{p_o}{V_{in}} + \frac{T_s \cdot V_{in} \cdot (v_o - V_{in})}{2L \cdot v_o}, \quad (14)$$

$$i_{L1bv} = \frac{p_o}{V_{in}} - \frac{T_s \cdot V_{in} \cdot (v_o - V_{in})}{2L \cdot v_o}. \quad (15)$$

It can be seen from Eqs. (12), (13) that in the step-down mode, the inductor current is the largest when the circuit is fully loaded,  $\cos \varphi = 0.75$  and  $v_o = 0$ . From Eqs. (14), (15), it can be seen that the inductor current is the largest in the step-up mode when the circuit is fully loaded,  $\cos \varphi = 1$  and  $v_o = V_m$ . Considering that the steady-state component and fluctuations of the inductor current in the step-up mode are greater than those in the step-down mode, thus the maximum inductor current in an LF cycle occurs at the moment when the output power is the maximum in the resistive full-load step-up mode. Suppose the maximum value of the inductor current is  $i_{L \max}$ , then the inductance satisfies:

$$L \geq \frac{V_{in} \cdot T_s \cdot (V_m - V_{in})}{2V_m \cdot \left( i_{L \max} - \frac{P_o \max}{V_{in}} \right)}. \quad (16)$$

## 6. Output CL filter design

The output side of the proposed inverter adopts a CL filter. It can be seen from Fig. 1 that the relationship between  $i_m$  and  $v_o$  is

$$i_m = \frac{v_o}{Z_L} + \frac{C_f L_f}{Z_L} \frac{d^2 v_o}{dt^2} + C_f \frac{dv_o}{dt}. \quad (17)$$

Therefore, the transfer function  $G(s)$  from  $v_o$  to  $i_m$  is

$$G(s) = \frac{V_o(s)}{I_m(s)} = \frac{Z_L \cdot \omega_n^2}{s^2 + 2\xi\omega_n s + \omega_n^2}, \quad (18)$$

where the natural oscillation frequency and damping ratio of the filter are

$$\begin{cases} \omega_n = \frac{1}{\sqrt{L_f C_f}} \\ \xi = \frac{Z_L \sqrt{L_f C_f}}{2} \end{cases}.$$

$\omega_n$  of the filter, the switching frequency  $f_s$  and the output voltage frequency  $f_0$  need to satisfy:

$$10f_0 \leq \frac{\omega_n}{2\pi} \leq 0.1f_s. \quad (19)$$

## 7. Simulation analysis

Simulation has been performed for the proposed circuit using circuit simulation software (PSIM). The simulation parameters are as follows: rated capacity  $S = 1000$  VA, input voltage  $V_{in} = 100\text{--}200$  V, output voltage  $V_o = 220$  V/50 Hz AC, power factor  $\cos \varphi$  is capacitive 0.75–1 – inductive 0.75, switching frequency  $f_s = 50$  kHz, an input filter capacitor  $C_{in} = 220$   $\mu$ F, output filter inductance  $L_f = 1$  mH, an output filter capacitor  $C_f = 10$   $\mu$ F, inductance  $L_1 = L_2 = 0.2$  mH. According to the capacity of the circuit, the voltage and current stress of the device and the corresponding device parameters, in the simulation, the on-state resistance of each switch is set to 60 m $\Omega$ , the equivalent junction capacitance of the switch is 280 pF, and the equivalent resistance of each winding coil of the coupled inductor is 10 m $\Omega$ .

Figure 6 is the simulation waveform diagram of the inverter. The simulation results indicate that:

1. The ideal drain-source voltage envelopes of  $S_{1a}$ ,  $S_{1b}$ ,  $S_{2a}$ , and  $S_{2b}$  in step-up and step-down modes are  $2V_{in} + v_o$  and  $2V_{in} - v_o$ , respectively. In the simulation, the drain-source voltage is relatively high due to leakage inductance. The drain-source voltage envelope of  $S_{3a}$ ,  $S_{3b}$ ,  $S_{4a}$ , and  $S_{4b}$  is  $v_o$ .
2. The waveforms of  $i_{L1}$  and  $i_{L2}$  are consistent with the theoretical results, whose maximum value falls within the designed 25 A.
3. In Figs. 6(d)–(f), the inverter performs well with resistive, capacitive and inductive loads. The output voltage THD is 1.45%, 1.56% and 1.84%, and the output current THD is 1.45%, 2.02% and 0.61%.

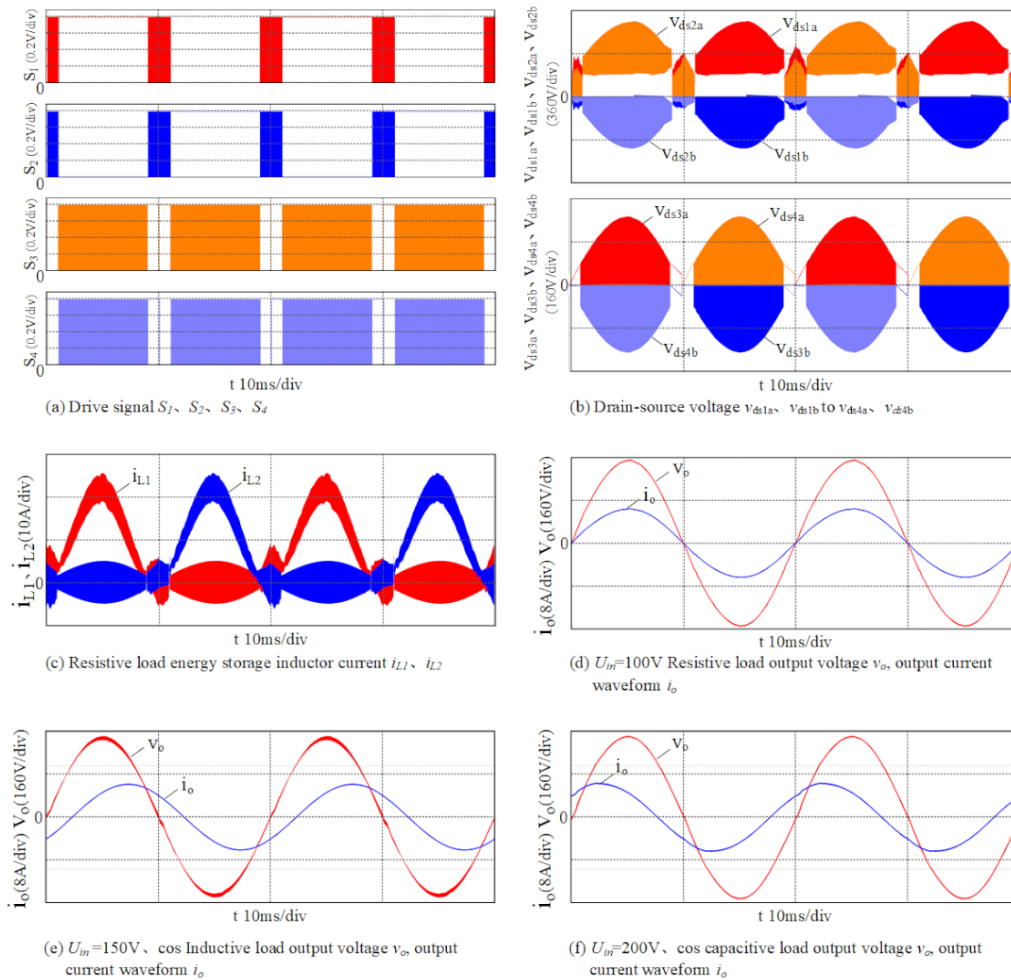


Fig. 6. Full-load steady-state simulation waveform of the inverter: drive signals  $S_1$ ,  $S_2$ ,  $S_3$ ,  $S_4$  (a); drain-source voltage  $v_{ds1a}$ ,  $v_{ds1b}$  to  $v_{ds4a}$ ,  $v_{ds4b}$  (b); resistive load energy storage inductor current  $i_{L1}$ ,  $i_{L2}$  (c);  $V_{in} = 100\text{ V}$  resistive load output voltage  $v_o$ , output current  $i_o$  (d);  $V_{in} = 150\text{ V}$ ,  $\cos \varphi = 0.75$  inductive load output voltage  $v_o$ , output current  $i_o$  (e);  $V_{in} = 200\text{ V}$ ,  $\cos \varphi = 0.75$  capacitive load output voltage  $v_o$ , output current  $i_o$  (f)

The dynamic simulation waveform of the proposed inverter is shown in Fig. 7. When the load changes from resistive half load to resistive full load, the waveform of  $v_o$  stabilizes quickly, and the dynamic response time is about 3 ms. When the input voltage  $V_{in}$  changes from 100 V to 120 V,  $v_o$  and  $i_o$  also behave well, its dynamic response time is about 2.5 ms.

Table 2 provides a comparison between the proposed inverter and the other three inverters in terms of circuit parameters and performance. It can be seen from the data in Table 2 that the output voltage THD of the proposed inverter under resistive load is 1.45%, and the efficiency is

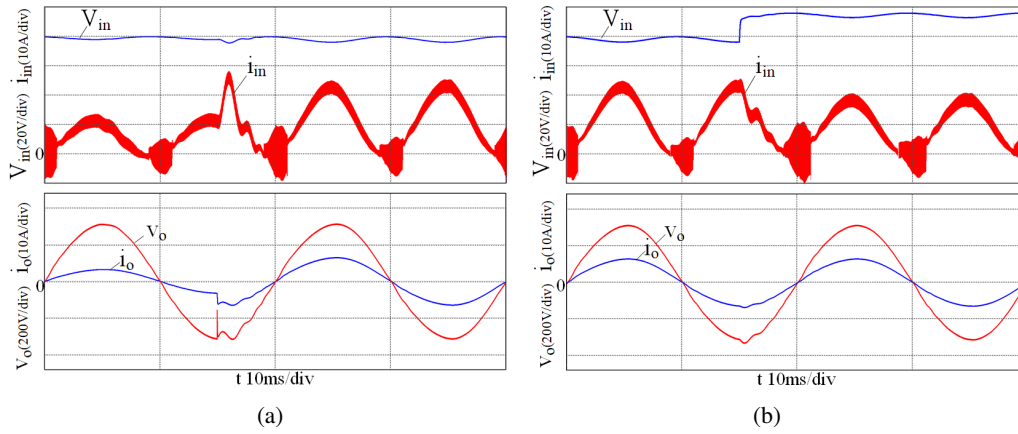


Fig. 7. Dynamic simulation waveform of the inverter: resistive half load to resistive full load (a); resistive full load  $V_{in}$  switches from 100 V to 120 V (b)

96.76%. Compared with other circuits, the proposed inverter requires fewer passive components and has higher efficiency, as well as can achieve a good output waveform through a simple control loop, but the switching voltage stress is relatively high.

Table 2. Comparison between the proposed inverter and the inverter in reference [22–24]

	Ref [22]	Ref [23]	Ref [24]	Proposed Inverter
Energy storage inductor	1 mH × 2	0.55 mH × 2	1 mH × 3	0.2 mH × 2
Energy storage capacitor	1 μF × 2	5 μF × 2	1 μF × 4	–
Filter inductance	1 mH	–	1.2 mH	1 mH
Filter capacitor	1 μF	–	1 μF	10 μF
Num. of switches	6	4	4	8
Num. of diodes	2	–	2	–
Maximum voltage stress	$V_m$	$\frac{2V_m V_{in}}{V_m + 2V_{in} - \sqrt{V_m^2 + 4V_{in}^2}}$	$\frac{3V_m - V_{in}}{2}$	$2V_{in} + V_m$
Boost ratio	$\frac{1}{1-D}$	$\frac{1-2D}{D(1-D)}$	$\frac{1}{1-3D}$	$\frac{1}{1-D}$
THD	1.84%	1.81%	1.7%	1.45%
Efficiency	96.78%	92.5%	91.6%	96.76%

## 8. Conclusions

1. A novel magnetically-coupled energy storage inductor boost inverter circuit topology is proposed. The circuit is composed of the cascaded input source  $V_{in}$ , the input filter  $C_{in}$ , a single-phase inverter bridge with a magnetic coupled energy storage inductor, and a  $CL$  filter. This single-phase inverter bridge consists of magnetically-coupled energy storage inductors and 4 four-quadrant power switches. It has two operating modes and four circuit modes. The coupled inductor can realize the magnetic potential balance of each switching cycle in the inverter's step-up conversion and step-down conversion.
2. The dual-mode control strategy with the feedback of the instantaneous value of the output voltage can smoothly switch between the two operation modes according to the output voltage error, and the instantaneous forward and reverse power flow of resistive, capacitive and inductive loads can be achieved.
3. In-depth analysis of the voltage transmission characteristics of the inverter, calculation of the time domain value of the duty cycle, and the parameter design method of the magnetically-coupled energy storage inductor and the output filter is provided.
4. Simulation results of PSIM show that the proposed inverter can realize single-stage boost power conversion, can adapt to resistive, capacitive and inductive loads, has the characteristics of high power density, low output waveform distortion, etc., and is suitable for the wider input voltage range of small and medium power boost inverter occasions.

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