# Synchronous Versions of Regulated Grammars: Generative Power and Linguistic Applications 

Petr Horáček, Alexander Meduna<br>Formal Model Research Group, Department of Information Systems, Faculty of Information Technology, Brno University of Technology, Božetěchova $1 / 2,61266$ Brno, Czech Republic ihoracekp@fit.vutbr.cz, meduna@fit.vutbr.cz<br>Received 20 June 2012, Revised 30 August 2012, Accepted 18 September 2012.


#### Abstract

This paper introduces the notion of new synchronous grammars as systems consisting of two context-free grammars with linked rules instead of linked nonterminals. Further, synchronous versions of regulated grammars, specifically, matrix grammars and scattered context grammars, are discussed. From a theoretical point of view, this paper discusses the power of these synchronous grammars. It demonstrates the following main results. First, if we synchronize context-free grammars by linking rules, the grammar generates the languages defined by matrix grammars. Second, if we synchronize matrix grammars by linking matrices, the generative power remains unchanged. Third, synchronous scattered context grammars generate the class of recursively enumerable languages. From a more practical viewpoint, this paper presents linguistic application prospects. The focus is on natural language translation between Japanese and English.


Keywords: regulated grammar, synchronous grammar, generative power, natural language translation

## 1. Introduction

Language-translation devices fulfill a significant role in the theory of formal languages. Apart from their theoretically oriented investigation, they are frequently applied in a variety of computer science fields, such as natural language translation. The present paper contributes to the study of synchronous versions of these devices.

To express the subject of this paper as well as its achieved results in a greater detail, recall there exists a generalization of context-free grammar (CFG) called synchronous CFG (see [3]), which strongly resembles syntax-directed transduction grammar [8] or syntax-directed translation scheme [1]. In essence, the synchronous CFG is a modification of CFG where every rule has two right-hand sides. In this way, the synchronous

CFGs represent translation-defining devices rather than language-defining devices as CFGs are traditionally used.

In [6], we have proposed synchronization based on linked rules instead of nonterminals. We have introduced synchronous matrix grammars and synchronous scattered context grammars. In this paper, we continue with this topic by discussing some theoretical properties of these grammars. Specifically, we investigate their generative power and achieve the following three main results.
I. First, if we synchronize CFGs by linking rules as proposed and defined in this paper, we obtain the generative power coinciding with the power of matrix grammars. Consequently, we significantly increase the power of CFGs in this way because the traditional synchronous CFGs (with linked nonterminals) only generate the family of context-free languages.
II. Second, we show that by synchronizing matrix grammars so we link matrices, we obtain no increase in power. That is, synchronous matrix grammars have the same generative power as matrix grammars.
III. Finally, we study synchronous scattered context grammars (with linked rules). We show that the class of languages defined by synchronous scattered context grammars equals the class of recursively enumerable languages.

In the conclusion of this paper, we sketch application perspectives of grammars discussed in this paper. We focus on Japanese-English translation and present examples illustrating the key principles and advantages of the new grammars. By extending the principle of synchronization beyond CFGs, we are able to describe certain syntactic structures and relations more easily. For example, when translating from Japanese to English, we need to deal with different handling of inflection. The translation is even more complicated by some important structural differences between the two languages.

## 2. Preliminaries

We assume that the reader is familiar with the basic aspects of modern formal language theory (see [12], [9]) and computational linguistics (see [11]). In this section, we review only selected definitions that are of key importance to the topics discussed in this paper. Further information about matrix grammars and scattered context grammars can be found in [4] and [10], respectively.
Definition 1 (Context-free grammar). A context-free grammar (CFG) G is a quadruple $G=(N, T, P, S)$, where $N$ is a finite set of nonterminals, $T$ is a finite set of terminals, $N \cap T=\emptyset, P \subset N \times(N \cup T)^{*}$ is a finite set of rules, $(u, v) \in P$ is written as $u \rightarrow v$, and $S \in N$ is the start symbol.

Definition 2 (Derivation). Let $G$ be a CFG. Let $u, v \in(N \cup T)^{*}$ and $p=A \rightarrow x \in P$. Then, we say that $u A v$ directly derives $u x v$ according to $p$ in $G$, written as $u A v \Rightarrow_{G}$
$u X v[p]$ or simply $u A v \Rightarrow u x v$. We further define $\Rightarrow^{+}$as the transitive closure of $\Rightarrow$ and $\Rightarrow^{*}$ as the transitive and reflexive closure of $\Rightarrow$.

Definition 3 (Generated language). Let $G$ be a $C F G$. The language generated by $G$, denoted by $L(G)$, is defined as $L(G)=\left\{w: w \in T^{*}, S \Rightarrow^{*} w\right\}$.

Definition 4 (Matrix grammar). A matrix grammar $H$ is a pair $H=(G, M)$, where $G=(N, T, P, S)$ is a $C F G$ and $M \subset P^{*}$ is a finite language over $P$. Members of $M$ are called matrices.

Definition 5 (Derivation in matrix grammar). Let $H=(G, M)$ be a matrix grammar, $G=(N, T, P, S)$. Then, for $u, v \in(N \cup T)^{*}, m \in M$ we define $u \Rightarrow v[m]$ in $H$, if there are strings $x_{0}, \ldots, x_{n}$ such that $u=x_{0}, v=x_{n}$ and $x_{0} \Rightarrow x_{1}\left[p_{1}\right] \Rightarrow x_{2}\left[p_{2}\right] \Rightarrow$ $\ldots \Rightarrow x_{n}\left[p_{n}\right]$ in $G$, and $m=p_{1} \ldots p_{n}$.

Definition 6 (Scattered context grammar). A scattered context grammar (SCG) G is a quadruple $G=(N, T, P, S)$, where $N$ is a finite set of nonterminals, $T$ is a finite set of terminals, $N \cap T=\emptyset, P$ is a finite set of rules of the form $\left(A_{1}, \ldots, A_{n}\right) \rightarrow\left(x_{1}, \ldots, x_{n}\right)$, where $A_{1}, \ldots, A_{n} \in N, x_{1}, \ldots, x_{n} \in(N \cup T)^{*}$, and $S \in N$ is the start symbol.

Definition 7 (Derivation in SCG). Let $G=(N, T, P, S)$ be an $S C G$. For $u, v \in(N \cup$ $T)^{*}, p \in P$ we define $u \Rightarrow v[p]$, if there is a factorization of $u=u_{1} A_{1} \ldots u_{n} A_{n} u_{n+1}$, $v=u_{1} x_{1} \ldots u_{n} x_{n} u_{n+1}$ such that $p=\left(A_{1}, \ldots, A_{n}\right) \rightarrow\left(x_{1}, \ldots, x_{n}\right)$ and $u_{i} \in(N \cup T)^{*}$ for $1 \leq i \leq n$.

## 3. Synchronization and Regulated Rewriting

This section recalls basic definitions from [6]. First, we define rule-based synchronization for CFGs.

Definition 8 (Rule-synchronized CFG). A rule-synchronized CFG (RSCFG) $H$ is a 5-tuple $H=\left(G_{I}, G_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$, where $G_{I}=\left(N_{I}, T_{I}, P_{I}, S_{I}\right)$ and $G_{O}=$ $\left(N_{O}, T_{O}, P_{O}, S_{O}\right)$ are CFGs, $\Psi$ is a set of rule labels, and $\varphi_{I}$ is a function from $\Psi$ to $P_{I}$ and $\varphi_{O}$ is a function from $\Psi$ to $P_{O}$.

We use the following notation (presented for input grammar $G_{I}$, analogous for output grammar $G_{O}$ ):

| $p: A_{I} \rightarrow x_{I}$ | $\varphi_{I}(p)=A_{I} \rightarrow x_{I}$ |
| :--- | :--- |
| where $p \in \Psi, A_{I} \rightarrow x_{I} \in P_{I}$ |  |
| $x_{I} \Rightarrow_{G_{I}} y_{I}[p]$ | derivation step in $G_{I}$ |
| where $x_{I}, y_{I} \in(N \cup T)^{*}, p \in \Psi$ | applying rule $\varphi_{I}(p)$ |
| $x_{I} \Rightarrow_{G_{I}}^{n} y_{I}\left[p_{1} \ldots p_{n}\right]$ | derivation in $G_{I}$ applying |
| where $x_{I}, y_{I} \in(N \cup T)^{*}, p_{i} \in \Psi$ for $1 \leq i \leq n$ | rules $\varphi_{I}\left(p_{1}\right) \ldots \varphi_{I}\left(p_{n}\right)$ |

Definition 9 (Translation in RSCFG). Let $H=\left(G_{I}, G_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$ be a RSCFG. Translation defined by $H, T(H)$, is the set of pairs of sentences, which is defined as $T(H)=\left\{\left(w_{I}, w_{O}\right): w_{I} \in T_{I}^{*}, w_{O} \in T_{O}^{*}, S_{I} \Rightarrow_{G_{I}}^{*} w_{I}[\alpha], S_{O} \Rightarrow_{G_{O}}^{*} w_{O}[\alpha], \alpha \in \Psi^{*}\right\}$.

In [6], we considered RSCFG only as a variant of synchronous CFG. However, there is in fact a significant difference. While the latter does not increase the generative power over CFG, RSCFG does as we prove in the next section.

Next, to define synchronization for SCGs, we simply replace context-free rules with scattered context rules.

Definition 10 (Synchronous SCG). A synchronous SCG (SSCG) $H$ is a 5-tuple $H=$ $\left(G_{I}, G_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$, where $G_{I}=\left(N_{I}, T_{I}, P_{I}, S_{I}\right)$ and $G_{O}=\left(N_{O}, T_{O}, P_{O}, S_{O}\right)$ are SCGs, $\Psi$ is a set of rule labels, and $\varphi_{I}$ is a function from $\Psi$ to $P_{I}$ and $\varphi_{O}$ is a function from $\Psi$ to $P_{O}$.

Definition 11 (Translation in SSCG). Let $H=\left(G_{I}, G_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$ be a SSCG. Translation defined by $H, T(H)$, is the set of pairs of sentences, which is defined as $T(H)=\left\{\left(w_{I}, w_{O}\right): w_{I} \in T_{I}^{*}, w_{O} \in T_{O}^{*}, S_{I} \Rightarrow_{G_{I}}^{*} w_{I}[\alpha], S_{O} \Rightarrow_{G_{O}}^{*} w_{O}[\alpha], \alpha \in \Psi^{*}\right\}$.

Finally, in matrix grammars, we link whole matrices rather than individual rules.
Definition 12 (Synchronous matrix grammar). A synchronous matrix grammar (SMAT) $H$ is a 7 -tuple $H=\left(G_{I}, M_{I}, G_{O}, M_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$, where $\left(G_{I}, M_{I}\right)$ and $\left(G_{O}, M_{O}\right)$ are matrix grammars, $\Psi$ is a set of matrix labels, and $\varphi_{I}$ is a function from $\Psi$ to $M_{I}$ and $\varphi_{O}$ is a function from $\Psi$ to $M_{O}$.

Definition 13 (Translation in SMAT). Let $H=\left(G_{I}, M_{I}, G_{O}, M_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$ be a SMAT. Translation defined by $H, T(H)$, is the set of pairs of sentences, which is defined as $T(H)=\left\{\left(w_{I}, w_{O}\right): w_{I} \in T_{I}^{*}, w_{O} \in T_{O}^{*}, S_{I} \Rightarrow_{\left(G_{I}, M_{I}\right)}^{*} w_{I}[\alpha], S_{O} \Rightarrow_{\left(G_{O}, M_{O}\right)}^{*}\right.$ $\left.w_{O}[\alpha], \alpha \in \Psi^{*}\right\}$.

## 4. Generative Power of Synchronous Grammars

Synchronous grammars define translation - that is, pairs of sentences. To be able to compare their generative power with well-known models such as CFGs, we can consider their input or output language.

Definition 14 (Input and output language). Let $H$ be a synchronous grammar. Then, we define
I. the input language of $H, L_{I}(H)$, as $L_{I}(H)=\left\{w_{I} \in T_{I}^{*}:\left(w_{I}, w_{O}\right) \in T(H)\right\}$,
II. the output language of $H, L_{O}(H)$, as $L_{O}(H)=\left\{w_{O} \in T_{O}^{*}:\left(w_{I}, w_{O}\right) \in T(H)\right\}$.

Example 1. Consider a RSCFG $H=\left(G_{I}, G_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$ with the following rules (nonterminals are in capitals, linked rules share the same label):

| $G_{I}$ |  |  |  | $G_{O}$ |  |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $1:$ | $S_{I}$ | $\rightarrow$ | $A B C$ | $1:$ | $S_{O}$ | $\rightarrow$ | $A$ |
| $2:$ | $A$ | $\rightarrow$ | $a A$ | $2:$ | $A$ | $\rightarrow$ | $B$ |
| $3:$ | $B$ | $\rightarrow$ | $b B$ | $3:$ | $B$ | $\rightarrow$ | $C$ |
| $4:$ | $C$ | $\rightarrow$ | $c C$ | $4:$ | $C$ | $\rightarrow$ | $A$ |
| $5:$ | $A$ | $\rightarrow$ | $\varepsilon$ | $5:$ | $A$ | $\rightarrow$ | $B^{\prime}$ |
| $6:$ | $B$ | $\rightarrow$ | $\varepsilon$ | $6:$ | $B^{\prime}$ | $\rightarrow$ | $C^{\prime}$ |
| $7:$ | $C$ | $\rightarrow$ | $\varepsilon$ | $7:$ | $C^{\prime}$ | $\rightarrow$ | $\varepsilon$ |

An example of a derivation follows next.

$$
\begin{array}{rlrlll}
S_{I} & \Rightarrow A B C & {[1]} & S_{O} & \Rightarrow & A \\
{[1]} \\
& \Rightarrow a A B C & {[2]} & & \Rightarrow & B \\
{[2]} \\
& \Rightarrow a A b B C & {[3]} & & \Rightarrow & C \\
& \Rightarrow 3] \\
& \Rightarrow a A b B c C & {[4]} & & \Rightarrow & B \\
& \Rightarrow a a A b B c C & {[2]} & & \Rightarrow & C \\
& \Rightarrow a a A b b B c C & {[3]} & & \Rightarrow & A \\
& \Rightarrow a a A b b B c c C & {[4]} & & \Rightarrow & B^{\prime} \\
& \Rightarrow a a b b B c c C & {[5]} & & \Rightarrow & C^{\prime} \\
& \Rightarrow 6] \\
& \Rightarrow a a b b c c C & {[6]} & & \Rightarrow & \varepsilon \\
& \Rightarrow a a b b c c & {[7]} & & &
\end{array}
$$

We can easily see that $L_{I}(H)=\left\{a^{n} b^{n} c^{n}: n \geq 0\right\}$, which is well known not to be a context-free language. This shows that RSCFGs are stronger than (synchronous) CFGs. Where exactly do synchronous grammars (rule-synchronized) stand in terms of generative power?

Let $\mathscr{L}(R S C F G), \mathscr{L}(S M A T)$, and $\mathscr{L}(S S C G)$ denote the class of languages generated by RSCFGs, SMATs, and SSCGs, respectively, as their input language. Note that the results presented below would be the same if we considered the output language instead.

Definition 15. Let $G=(N, T, P, S)$ be a $C F G$. Then, we define the function $\Delta$ over $(N \cup T)^{*}$ as follows:
I. for all $w \in T^{*}, \Delta(w)=\varepsilon$
II. for all $w=x_{0} A_{1} x_{2} A_{2} \ldots x_{n-1} A_{n} x_{n}, x_{i} \in T^{*}, 0 \leq i \leq n, A_{j} \in N, 1 \leq j \leq n$ for some $n \geq 1, \Delta(w)=A_{1} A_{2} \ldots A_{n}$.

In this paper, we demonstrate the following main results.

## Theorem 1.

$$
\mathscr{L}(R S C F G)=\mathscr{L}(M A T)
$$

Proof. I. First, we prove that $\mathscr{L}(R S C F G) \subseteq \mathscr{L}(M A T)$. For every RSCFG $H=$ $\left(G_{I}, G_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$, where $G_{I}=\left(N_{I}, T_{I}, P_{I}, S_{I}\right), G_{O}=\left(N_{O}, T_{O}, P_{O}, S_{O}\right)$, we can construct a matrix grammar $H^{\prime}=(G, M)$, where $G=(N, T, P, S)$, such that $L\left(H^{\prime}\right)=$ $L_{I}(H)$, as follows. Without loss of generality, assume $N_{I} \cap N_{O}=\emptyset, S \notin N_{I} \cup N_{O}$. Set $N=N_{I} \cup N_{O} \cup\{S\}, T=T_{I}, P=\left\{S \rightarrow S_{I} S_{O}\right\}, M=\left\{S \rightarrow S_{I} S_{O}\right\}$. For every label $p \in \Psi$, add rules $p_{I}$, $p_{O}$ to $P$, add matrix $p_{I} p_{O}$ to $M$, where $p_{I}=\varphi_{I}(p)$ and $p_{O}=A \rightarrow x$ such that $\varphi_{O}(p)=A \rightarrow x^{\prime}, x=\Delta\left(x^{\prime}\right) .{ }^{1}$

Basic idea. $H^{\prime}$ simulates the principle of linked rules in $H$ by matrices. That is, for every pair of rules $\left(A_{I} \rightarrow x_{I}, A_{O} \rightarrow x_{O}\right)$ such that $\varphi_{I}(p)=A_{I} \rightarrow x_{I}, \varphi_{O}(p)=$ $A_{O} \rightarrow x_{O}$ for some $p \in \Psi$ in $H$, there is a matrix $m=A_{I} \rightarrow x_{I} A_{O} \rightarrow \Delta\left(x_{O}\right)$ in $H^{\prime}$. If, in $H, x_{I} \Rightarrow y_{I}[p]$ in $G_{I}$ and $x_{O} \Rightarrow y_{O}[p]$ in $G_{O}$, then there is a derivation step $x_{I} \Delta\left(x_{O}\right) \Rightarrow y_{I} \Delta\left(y_{O}\right)[m]$ in $H^{\prime}$. Note that since the rules are context-free, the presence (or absence) of terminals in a sentential form does not affect which rules we can apply. Furthermore, because the nonterminal sets $N_{I}$ and $N_{O}$ are disjoint, the sentential form in $H^{\prime}$ always consists of two distinct parts such that the first part corresponds to the derivation in $G_{I}$ and the second part to the derivation in $G_{O}$.

Claim 2. If $S_{I} \Rightarrow^{*} w_{I}[\alpha], S_{O} \Rightarrow^{*} w_{O}[\alpha]$ in $H$ for some $\alpha \in \Psi^{*}$, then $S \Rightarrow^{*} w_{I} \Delta\left(w_{O}\right)$ in $H^{\prime}$.

Proof of Claim 2. By induction on the number of derivation steps in $H$.
Basis. Let $S_{I} \Rightarrow^{0} S_{I}[\varepsilon], S_{O} \Rightarrow^{0} S_{O}[\varepsilon]$ in $H$. Then, $S \Rightarrow S_{I} S_{O}[p]$ in $G, p \in M$, and thus $S \Rightarrow S_{I} S_{O}[p]$ in $H^{\prime}$. Claim 2 holds for zero derivation steps in $H$.

Induction hypotesis. Suppose that Claim 2 holds for $j$ or fewer derivation steps in $H$.

Induction step. Let $S_{I} \Rightarrow^{j} w_{I}[\alpha] \Rightarrow w_{I}^{\prime}[p], S_{O} \Rightarrow^{j} w_{O}[\alpha] \Rightarrow w_{O}^{\prime}[p]$ in $H$. Then, by the induction hypotesis, $S \Rightarrow^{*} w_{I} \Delta\left(w_{O}\right)$ in $H^{\prime}$. Without loss of generality, suppose that $w_{I}=u_{I} A_{I} v_{I}, w_{O}=u_{O} A_{O} v_{O}, w_{I}^{\prime}=u_{I} x_{I} v_{I}, w_{O}^{\prime}=u_{O} x_{O} v_{O}$, where $A_{I} \in N_{I}, A_{O} \in N_{O}, u_{I}, v_{I}, x_{I} \in\left(N_{I} \cup T_{I}\right)^{*}$, and $u_{O}, v_{O}, x_{O} \in\left(N_{O} \cup T_{O}\right)^{*}$. That is, $\varphi_{I}(p)=A_{I} \rightarrow x_{I}, \varphi_{O}(p)=A_{O} \rightarrow x_{O}$. From the construction of $H^{\prime}$, we know that $p_{I}=A_{I} \rightarrow x_{I} \in P, p_{O}=A_{O} \rightarrow \Delta\left(x_{O}\right) \in P$, and $p_{I} p_{O} \in M$. Therefore, in $H^{\prime}, S \Rightarrow^{*} w_{I} \Delta\left(w_{O}\right)=u_{I} A_{I} v_{I} \Delta\left(u_{O} A_{O} v_{O}\right) \Rightarrow u_{I} x_{I} v_{I} \Delta\left(u_{O} x_{O} v_{O}\right)\left[p_{I} p_{O}\right]=$ $w_{I} \Delta\left(w_{O}\right)$. Claim 2 holds. Furthermore, if $S_{I} \Rightarrow^{*} w_{I}[\alpha], S_{O} \Rightarrow^{*} w_{O}[\alpha]$ in $H$, where $w_{I} \in T_{I}^{*}, w_{O} \in T_{O}^{*}$, then $\Delta\left(w_{O}\right)=\varepsilon$, and thus $S \Rightarrow^{*} w_{I}$ in $H^{\prime} . L_{I}(H) \subseteq L\left(H^{\prime}\right)$.

[^0]Claim 3. If $S \Rightarrow^{*} w$ in $H^{\prime}$, then there are strings $w_{I}, w_{O}$ such that $w=w_{I} \Delta\left(w_{O}\right)$ and $S_{I} \Rightarrow^{*} w_{I}[\alpha], S_{O} \Rightarrow^{*} w_{O}[\alpha]$ in $H$ for some $\alpha \in \Psi^{*}$.

Proof of Claim 3. By induction on the number of derivation steps in $H^{\prime}$.
Basis. Consider a single derivation step in $H^{\prime}$. Because $S \rightarrow S_{I} S_{O}$ is the only rule in $P$ with $S$ as its left-hand side, this must be $S \Rightarrow S_{I} S_{O}$. Then, $S_{I} \Rightarrow^{0} S_{I}[\varepsilon]$, $S_{O} \Rightarrow{ }^{0} S_{O}[\varepsilon]$ in $H$. Claim 3 holds for one derivation step in $H^{\prime}$.

Induction hypotesis. Suppose that Claim 3 holds for $j$ or fewer derivation steps in $H^{\prime}$.

Induction step. Let $S \Rightarrow S_{I} S_{O} \Rightarrow^{j-1} w \Rightarrow w^{\prime}[m]$ in $H^{\prime}$. Then, by the induction hypotesis, $S_{I} \Rightarrow^{*} w_{I}[\alpha], S_{O} \Rightarrow^{*} w_{O}[\alpha]$ in $H$ for some $w_{I}, w_{O}$ such that $w=w_{I} \Delta\left(w_{O}\right)$. From the construction of $H^{\prime}$, we know that $m=p_{I} p_{O}$, where for some $p \in \Psi, p_{I}=A_{I} \rightarrow x_{I}=\varphi_{I}(p)$ and $p_{O}=A_{O} \rightarrow \Delta\left(x_{O}\right)$ such that $A_{O} \rightarrow x_{O}=\varphi_{O}(p)$. Therefore, there must be a factorization of $w$ and $w^{\prime}$ such that $w=w_{I} \Delta\left(w_{O}\right)=u_{I} A_{I} v_{I} \Delta\left(u_{O} A_{O} v_{O}\right), w^{\prime}=w_{I}^{\prime} \Delta\left(w_{O}^{\prime}\right)=u_{I} x_{I} v_{I} \Delta\left(u_{O} x_{O} v_{O}\right)$ where $A_{I} \in N_{I}, A_{O} \in N_{O}, u_{I}, v_{I}, x_{I} \in\left(N_{I} \cup T_{I}\right)^{*}$, and $u_{O}, v_{O}, x_{O} \in\left(N_{O} \cup T_{O}\right)^{*}$. Therefore, $S_{I} \Rightarrow^{*} w_{I}[\alpha]=u_{I} A_{I} v_{I} \Rightarrow u_{I} x_{I} v_{I}[p]=w_{I}^{\prime}$ and $S_{O} \Rightarrow^{*} w_{O}[\alpha]=$ $u_{O} A_{O} v_{O} \Rightarrow u_{O} x_{O} v_{O}[p]=w_{O}^{\prime}$ in $H$. Claim 3 holds. Furthermore, if $S \Rightarrow^{*} w$ in $H^{\prime}$, where $w \in T^{*}$, then $w_{I} \in T_{I}^{*}$ and $\Delta\left(w_{O}\right)=\varepsilon$, thus $w_{O} \in T_{O}^{*} . L\left(H^{\prime}\right) \subseteq L_{I}(H)$.
II. Now we have to show that $\mathscr{L}(M A T) \subseteq \mathscr{L}(R S C F G)$ holds. For every matrix grammar $H=(G, M)$, where $G=(N, T, P, S)$, we can construct a RSCFG $H^{\prime}=$ $\left(G_{I}, G_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$, where $G_{I}=\left(N_{I}, T_{I}, P_{I}, S_{I}\right), G_{O}=\left(N_{O}, T_{O}, P_{O}, S_{O}\right)$, such that $L_{I}\left(H^{\prime}\right)=L(H)$, as follows. Without loss of generality, assume $N \cap\left\{S_{I}, S_{O}, X\right\}=$ $\emptyset$. Set $N_{I}=N \cup\left\{S_{I}, X\right\}, T_{I}=T, P_{I}=\left\{S_{I} \rightarrow S X, X \rightarrow \varepsilon\right\}, N_{O}=\left\{S_{O}, X\right\}$, $T_{O}=\emptyset, P_{O}=\left\{S_{O} \rightarrow X, X \rightarrow \varepsilon\right\}$. Set $\Psi=\{0,1\}, \varphi_{I}=\emptyset, \varphi_{O}=\emptyset, \varphi_{I}(0)=$ $S_{I} \rightarrow S X, \varphi_{O}(0)=S_{O} \rightarrow X, \varphi_{I}(1)=X \rightarrow \varepsilon, \varphi_{O}(1)=X \rightarrow \varepsilon$. For every matrix $m=p \in M$, where $p \in P$, add rule $p$ to $P_{I}, X \rightarrow X$ to $P_{O}$, add label $\langle m\rangle$ to $\Psi$, and set $\varphi_{I}(\langle m\rangle)=p, \varphi_{O}(\langle m\rangle)=X \rightarrow X$. For every matrix $m=p_{1} \ldots p_{n} \in M$, where $n>1$, add rules $p_{1}, \ldots, p_{n}$ to $P_{I}$, add new nonterminals $\langle X m\rangle_{1}, \ldots,\langle X m\rangle_{n-1}$ to $N_{O}$, add rules $X \rightarrow\langle X m\rangle_{1},\langle X m\rangle_{1} \rightarrow\langle X m\rangle_{2}, \ldots,\langle X m\rangle_{n-2} \rightarrow\langle X m\rangle_{n-1},\langle X m\rangle_{n-1} \rightarrow X$ to $P_{O}$, add new labels $\langle m\rangle_{1}, \ldots,\langle m\rangle_{n}$ to $\Psi$, and set $\varphi_{I}\left(\langle m\rangle_{1}\right)=p_{1}, \varphi_{O}\left(\langle m\rangle_{1}\right)=X \rightarrow\langle X m\rangle_{1}$, $\varphi_{I}\left(\langle m\rangle_{i}\right)=p_{i}, \varphi_{O}\left(\langle m\rangle_{i}\right)=\langle X m\rangle_{i-1} \rightarrow\langle X m\rangle_{i}$ for $1<i<n$, and $\varphi_{I}\left(\langle m\rangle_{n}\right)=p_{n}$, $\varphi_{O}\left(\langle m\rangle_{n}\right)=\langle X m\rangle_{n-1} \rightarrow X$.

Basic idea. $H^{\prime}$ simulates matrices in $H$ by derivation in $G_{O}$. That is, if $x \Rightarrow y[m]$ in $H$, where $m=p_{1} \ldots p_{n}$ for some $n$, then there is a sequence of derivation steps $X \Rightarrow$ $\langle X m\rangle_{1}\left[\langle m\rangle_{1}\right] \Rightarrow\langle X m\rangle_{2}\left[\langle m\rangle_{2}\right] \Rightarrow \ldots \Rightarrow\langle X m\rangle_{n-2}\left[\langle m\rangle_{n-2}\right] \Rightarrow\langle X m\rangle_{n-1}\left[\langle m\rangle_{n-1}\right] \Rightarrow$ $X\left[\langle m\rangle_{n}\right]$ in $G_{O}$ and $\varphi_{I}\left(\langle m\rangle_{i}\right)=p_{i}$ for $1 \leq i \leq n$. Now observe that in $G_{O}$ constructed by the above algorithm, every nonterminal except $X$ can only appear as the left-hand
side of no more than one rule. This means that after rewriting $X$ to $\langle X m\rangle_{1}$, the only way for the derivation to proceed is the above sequence, and the entire matrix is simulated.

Formally, if $x \Rightarrow y[m]$ in $H$, where $m=p_{1} \ldots p_{n}$ for some $n$, then, in $H^{\prime}, x \Rightarrow^{n}$ $y\left[m_{1} \ldots m_{n}\right]$ in $G_{I}$ and $X \Rightarrow^{n} X\left[m_{1} \ldots m_{n}\right]$ in $G_{O}$. Conversely, if, in $H^{\prime}, x \Rightarrow^{n} y[\alpha]$ in $G_{I}$ and $X \Rightarrow^{n} X[\alpha]$ in $G_{O}$ for some $n \geq 1, \alpha \in \Psi^{*}$, and there is no $k<n$ such that $x \Rightarrow^{k} z[\beta] \Rightarrow^{*} y[\gamma]$ in $G_{I}$ and $X \Rightarrow^{k} X[\beta] \Rightarrow^{*} X[\gamma]$ in $G_{O}$ for some $\beta, \gamma \in \Psi^{*}$, there has to be $m \in M$ such that $x \Rightarrow y[m]$ in $H$. Therefore, if for some $\alpha \in \Psi^{*}, S_{I} \Rightarrow^{*}$ $w X[\alpha] \Rightarrow w[1], S_{O} \Rightarrow^{*} X[\alpha] \Rightarrow \varepsilon[1]$ in $H^{\prime}$, where $w \in T_{I}^{*}$, then $S \Rightarrow^{*} w$ in $H$. On the other hand, if $S \Rightarrow^{*} w$ in $H$, where $w \in T^{*}$, then $\alpha \in \Psi^{*}, S_{I} \Rightarrow^{*} w X[\alpha] \Rightarrow w[1]$, $S_{O} \Rightarrow^{*} X[\alpha] \Rightarrow \varepsilon[1]$ in $H^{\prime}$ for some $\alpha \in \Psi^{*} . L_{I}\left(H^{\prime}\right)=L(H)$.

Theorem 1 holds.

Note that $G_{O}$ constructed by the above algorithm is not only context-free, but also regular.

## Theorem 4.

$$
\mathscr{L}(S M A T)=\mathscr{L}(M A T)
$$

Proof. The inclusion $\mathscr{L}(M A T) \subseteq \mathscr{L}(S M A T)$ follows from definition. It only remains to prove that $\mathscr{L}(S M A T) \subseteq \mathscr{L}(M A T)$. For every SMAT $H=\left(G_{I}, M_{I}, G_{O}, M_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$, where $G_{I}=\left(N_{I}, T_{I}, P_{I}, S_{I}\right), G_{O}=$ $\left(N_{O}, T_{O}, P_{O}, S_{O}\right)$, we can construct a matrix grammar $H^{\prime}=(G, M)$, where $G=$ $(N, T, P, S)$, such that $L\left(H^{\prime}\right)=L_{I}(H)$, as follows. Without loss of generality, assume $N_{I} \cap N_{O}=\emptyset, S \notin N_{I} \cup N_{O}$. Set $N=N_{I} \cup N_{O} \cup\{S\}, T=T_{I}, P=\left\{S \rightarrow S_{I} S_{O}\right\}$, $M=\left\{S \rightarrow S_{I} S_{O}\right\}$. For every label $p \in \Psi$, add rules $p_{I 1}, \ldots, p_{I n}, p_{O 1}, \ldots, p_{O m}$ to $P$, add matrix $p_{I 1} \ldots p_{I_{n}} p_{O_{1}} \ldots p_{O m}$ to $M$, where $p_{I_{1}} \ldots p_{I_{n}}=\varphi_{I}(p)$ and for $1 \leq j \leq m$, $p_{O_{j}}=A_{j} \rightarrow x_{j}$ such that $\varphi_{O}(p)[j]=A_{j} \rightarrow x_{j}^{\prime}, x_{j}=\Delta\left(x_{j}^{\prime}\right) .^{2}$

Basic idea. $H^{\prime}$ simulates $H$ by combining the rules of each two linked matrices in $H$ into a single matrix in $H^{\prime}$. That is, for every pair of matrices $\left(m_{I}, m_{O}\right)$ such that $m_{I}=\varphi_{I}(p), m_{O}=\varphi_{O}(p)$ for some $p \in \Psi$ in $H$, there is a matrix $m=m_{I} m_{O}^{\prime}$ in $H^{\prime}$, where $m_{O}^{\prime}$ is equal to $m_{O}$ with all terminals removed (formally defined above). If, in $H$, $x_{I} \Rightarrow y_{I}[p]$ in $G_{I}$ and $x_{O} \Rightarrow y_{O}[p]$ in $G_{O}$, then there is a derivation step $x_{I} \Delta\left(x_{O}\right) \Rightarrow$ $y_{I} \Delta\left(y_{O}\right)[m]$ in $H^{\prime}$. Note that since the rules are context-free, the presence (or absence) of terminals in a sentential form does not affect which rules we can apply. Furthermore, because the nonterminal sets $N_{I}$ and $N_{O}$ are disjoint, the sentential form in $H^{\prime}$ always consists of two distinct parts such that the first part corresponds to the derivation in $G_{I}$ and the second part to the derivation in $G_{O}$.

[^1]Claim 5. If $S_{I} \Rightarrow^{*} w_{I}[\alpha], S_{O} \Rightarrow^{*} w_{O}[\alpha]$ in $H$ for some $\alpha \in \Psi^{*}$, then $S \Rightarrow^{*} w_{I} \Delta\left(w_{O}\right)$ in $H^{\prime}$.

Proof of Claim 5. By induction on the number of derivation steps in $H$.
Basis. Let $S_{I} \Rightarrow^{0} S_{I}[\varepsilon], S_{O} \Rightarrow^{0} S_{O}[\varepsilon]$ in $H$. Then, $S \Rightarrow S_{I} S_{O}[p]$ in $G, p \in M$, and thus $S \Rightarrow S_{I} S_{O}[p]$ in $H^{\prime}$. Claim 5 holds for zero derivation steps in $H$.

Induction hypotesis. Suppose that Claim 5 holds for $j$ or fewer derivation steps in $H$.
Induction step. Let $S_{I} \Rightarrow^{j} w_{I}[\alpha] \Rightarrow w_{I}^{\prime}[p], S_{O} \Rightarrow^{j} w_{O}[\alpha] \Rightarrow w_{O}^{\prime}[p]$ in $H$. Then, by the induction hypotesis, $S \Rightarrow^{*} w_{I} \Delta\left(w_{O}\right)$ in $H^{\prime}$. Furthermore, if $w_{I} \Rightarrow w_{I}^{\prime}[p]$ in $\left(G_{I}, M_{I}\right), w_{O} \Rightarrow w_{O}^{\prime}[p]$ in $\left(G_{O}, M_{O}\right)$, where $\varphi_{I}(p)=p_{I_{1} \ldots p_{I_{n}}}$ for some $n$, $\varphi_{O}(p)=p_{O_{1}} \ldots p_{O_{m}}$ for some $m$, then, in $G_{I}, w_{I} \Rightarrow w_{I_{1}}\left[p_{I_{1}}\right] \Rightarrow \ldots \Rightarrow w_{I_{n}}\left[p_{I_{n}}\right]=$ $w_{I}^{\prime}$, and, in $G_{O}, w_{O} \Rightarrow w_{O_{1}}\left[p_{O_{1}}\right] \Rightarrow \ldots \Rightarrow w_{O_{n}}\left[p_{O_{m}}\right]=w_{O}^{\prime}$. Without loss of generality, suppose that $w_{I}=u_{I 1} A_{I 1} v_{I 1} \Rightarrow u_{I 1} x_{I 1} v_{I 1}\left[p_{I 1}\right]=u_{I 2} A_{I 2} v_{I 2} \Rightarrow \ldots \Rightarrow$ $u_{I_{n}} x_{I n} v_{I n}\left[p_{I_{n}}\right]=w_{I}^{\prime}, w_{O}=u_{O_{1}} A_{O 0} v_{O 1} \Rightarrow u_{O_{1}} x_{O_{1}} v_{O_{1}}\left[p_{O_{1}}\right]=u_{O_{2}} A_{O_{2}} v_{O_{2}} \Rightarrow$ $\ldots \Rightarrow u_{O m} x_{O_{m}} v_{O m}\left[p_{O_{m}}\right]=w_{O}^{\prime}$, where for $1 \leq i \leq n, A_{I i} \in N_{I}, u_{I i}, v_{I i}, x_{I i} \in$ $\left(N_{I} \cup T_{I}\right)^{*}$, and for $1 \leq j \leq m, A_{O_{j}} \in N_{O}, u_{O j}, v_{O_{j}}, x_{O_{j}} \in\left(N_{O} \cup T_{O}\right)^{*}$. That is, $\varphi_{I}(p)=A_{I 1} \rightarrow x_{I 1} \ldots A_{I n} \rightarrow x_{I n}, \varphi_{O}(p)=A_{O 1} \rightarrow x_{O 1} \ldots A_{O m} \rightarrow x_{O m}$. From the construction of $H^{\prime}$, we know that for $1 \leq i \leq n, p_{I i}=A_{I i} \rightarrow x_{I i} \in P$, for $1 \leq j \leq m, p_{O j}^{\prime}=A_{O_{j}} \rightarrow \Delta\left(x_{O_{j}}\right) \in P$, and $t=p_{I_{1}} \ldots p_{I_{n}} p_{O 1}^{\prime} \ldots p_{O m}^{\prime} \in M$. Therefore, in $G, S \Rightarrow^{*} w_{I} \Delta\left(w_{O}\right)=u_{I 1} A_{I 1} v_{I 1} \Delta\left(w_{O}\right) \Rightarrow u_{I 1} x_{I 1} v_{I 1} \Delta\left(w_{O}\right)\left[p_{I_{1}}\right]=$ $u_{I 2} A_{I 2} v_{I 2} \Delta\left(w_{O}\right) \Rightarrow \ldots \Rightarrow u_{I_{n}} x_{I n} v_{I n} \Delta\left(w_{O}\right)\left[p_{I_{n}}\right] \quad=w_{I}^{\prime} \Delta w_{O}=$ $w_{I}^{\prime} \Delta\left(u_{O 1} A_{O 1} v_{O 1}\right) \Rightarrow w_{I}^{\prime} \Delta\left(u_{O 1} x_{O 1} v_{O 1}\right)\left[p_{O 1}^{\prime}\right]=w_{I}^{\prime} \Delta\left(u_{O 2} A_{O 2} v_{O 2}\right) \Rightarrow \ldots \Rightarrow$ $w_{I}^{\prime} \Delta\left(u_{O m} x_{O m} v_{O m}\right)\left[p_{O m}^{\prime}\right]=w_{I}^{\prime} \Delta\left(w_{O}^{\prime}\right)$, and thus in $H^{\prime}, S \Rightarrow^{*} w_{I} \Delta w_{O} \Rightarrow$ $w_{I}^{\prime} \Delta\left(w_{O}^{\prime}\right)[t]$. Claim 5 holds. Furthermore, if $S_{I} \Rightarrow^{*} w_{I}[\alpha], S_{O} \Rightarrow^{*} w_{O}[\alpha]$ in $H$, where $w_{I} \in T_{I}^{*}, w_{O} \in T_{O}^{*}$, then $\Delta\left(w_{O}\right)=\varepsilon$, and thus $S \Rightarrow^{*} w_{I}$ in $H^{\prime}$. $L_{I}(H) \subseteq L\left(H^{\prime}\right)$.

Claim 6. If $S \Rightarrow^{*} w$ in $H^{\prime}$, then there are strings $w_{I}$, $w_{O}$ such that $w=w_{I} \Delta\left(w_{O}\right)$ and $S_{I} \Rightarrow^{*} w_{I}[\alpha], S_{O} \Rightarrow^{*} w_{O}[\alpha]$ in $H$ for some $\alpha \in \Psi^{*}$.

Proof of Claim 6. By induction on the number of derivation steps in $H^{\prime}$.
Basis. Consider a single derivation step in $H^{\prime}$. Because $S \rightarrow S_{I} S_{O}$ is the only rule in $P$ with $S$ as its left-hand side, this must be $S \Rightarrow S_{I} S_{O}$. Then, $S_{I} \Rightarrow^{0} S_{I}[\varepsilon]$, $S_{O} \Rightarrow^{0} S_{O}[\varepsilon]$ in $H$. Claim 6 holds for one derivation step in $H^{\prime}$.

Induction hypotesis. Suppose that Claim 6 holds for $j$ or fewer derivation steps in $H^{\prime}$.

Induction step. Let $S \Rightarrow S_{I} S_{O} \Rightarrow^{j-1} w \Rightarrow w^{\prime}[t]$ in $H^{\prime}$. Then, by the induction hypotesis, $S_{I} \Rightarrow^{*} w_{I}[\alpha], S_{O} \Rightarrow^{*} w_{O}[\alpha]$ in $H$ for some $w_{I}, w_{O}$ such that $w=$ $w_{I} \Delta\left(w_{O}\right)$. From the construction of $H^{\prime}$, we know that $t=p_{I_{1}} \ldots p_{I_{n}} p_{O 1}^{\prime} \ldots p_{O m}^{\prime}$, where for some $p \in \Psi, p_{I 1}=A_{I 1} \rightarrow x_{I 1} \ldots p_{I_{n}}=A_{I_{n}} \rightarrow x_{I_{n}}=\varphi_{I}(p)$ and $p_{O 1}^{\prime}=A_{O 1} \rightarrow \Delta\left(x_{O}\right)_{1} \ldots p_{O n}^{\prime}=A_{O m} \rightarrow \Delta\left(x_{O m}\right)$ such that $p_{O_{1}}=A_{O 1} \rightarrow$
$x_{O 1} \ldots p_{O m}=A_{O m} \rightarrow x_{O m}=\varphi_{O}(p)$. Then, if $S \Rightarrow S_{I} S_{O} \Rightarrow^{j-1} w \Rightarrow w^{\prime}[t]$ in $H^{\prime}, S \Rightarrow^{*} w=w_{I} \Delta\left(w_{O}\right)=u_{I 1} A_{I 1} v_{I 1} \Delta\left(w_{O}\right) \Rightarrow u_{I 1} x_{I 1} v_{I 1} \Delta\left(w_{O}\right)\left[p_{I 1}\right]=$ $u_{I 2} A_{I 2} v_{I 2} \Delta\left(w_{O}\right) \quad \Rightarrow \quad \ldots \quad \Rightarrow \quad u_{I n} x_{I n} v_{I n} \Delta\left(w_{O}\right)\left[p_{I_{n}}\right] \quad=w_{I}^{\prime} \Delta w_{O} \quad=$ $w_{I}^{\prime} \Delta\left(u_{O_{1}} A_{O_{1}} v_{O_{1}}\right) \Rightarrow w_{I}^{\prime} \Delta\left(u_{O_{1}} x_{O_{1}} v_{O_{1}}\right)\left[p_{O_{1}}^{\prime}\right]=w_{I}^{\prime} \Delta\left(u_{O_{2}} A_{O_{2} v_{O 2}}\right) \Rightarrow \ldots \Rightarrow$ $w_{I}^{\prime} \Delta\left(u_{O m} x_{O m} v_{O m}\right)\left[p_{O m}^{\prime}\right]=w_{I}^{\prime} \Delta\left(w_{O}^{\prime}\right)$ in $G$, where for $1 \leq i \leq n, A_{I i} \in N_{I}$, $u_{I i}, v_{I i}, x_{I i} \in\left(N_{I} \cup T_{I}\right)^{*}$, and for $1 \leq j \leq m, A_{O_{j}} \in N_{O}, u_{O_{j}}, v_{O_{j}}, x_{O_{j}} \in$ $\left(N_{O} \cup T_{O}\right)^{*}$. Therefore, $w_{I}=u_{I 1} A_{I 1} v_{I 1} \Rightarrow u_{I 1} x_{I 1} v_{I 1}\left[p_{I 1}\right]=u_{I 2} A_{I 2} v_{I 2} \Rightarrow$ $\ldots \Rightarrow u_{I_{n}} x_{I n} v_{I n}\left[p_{I_{n}}\right]=w_{I}^{\prime}$ in $G_{I}$ and $w_{O}=u_{O_{1}} A_{O_{0} v_{O 1}} \Rightarrow u_{O_{1}} x_{O_{1}} v_{O_{1}}\left[p_{O_{1}}\right]=$ $u_{O 2} A_{O 2} v_{O 2} \Rightarrow \ldots \Rightarrow u_{O m} x_{O m} v_{O m}\left[p_{O m}\right]=w_{O}^{\prime}$ in $G_{O}$, and thus $S_{I} \Rightarrow^{*} w_{I}[\alpha]=$ $u_{I} A_{I} v_{I} \Rightarrow u_{I} x_{I} v_{I}[p]=w_{I}^{\prime}$ and $S_{O} \Rightarrow{ }^{*} w_{O}[\alpha]=u_{O} A_{O} v_{O} \Rightarrow u_{O} x_{O} v_{O}[p]=w_{O}^{\prime}$ in $H$. Claim 6 holds. Furthermore, if $S \Rightarrow^{*} w$ in $H^{\prime}$, where $w \in T^{*}$, then $w_{I} \in T_{I}^{*}$ and $\Delta\left(w_{O}\right)=\varepsilon$, thus $w_{O} \in T_{O}^{*} . L\left(H^{\prime}\right) \subseteq L_{I}(H)$.

Theorem 4 holds.

## Theorem 7.

$$
\mathscr{L}(S S C G)=R E
$$

Proof. Clearly, $\mathscr{L}(S S C G) \subseteq R E$ holds. From definition, it follows that $\mathscr{L}(S C G) \subseteq$ $\mathscr{L}(S S C G)$. Because $\mathscr{L}(S C G)=R E, R E \subseteq \mathscr{L}(S S C G)$ must also hold.

## 5. Applications in Natural Language Translation

In this section, we discuss possibilities of applications in linguistics. More specifically, we present examples of translating some grammatical structures from Japanese to English.

First, to demonstrate the basic principle, we consider a simple Japanese sentence

> Takeshi-san wa raishuu Oosaka ni ikimasu.

We will transform this sentence (or, more precisely, the structure of this sentence) into its English counterpart

## Takeshi is going to Osaka next week.

In the following examples, words in angled brackets $(\rangle)$ are words associated with a terminal or nonterminal symbol in a given sentence or structure. Note that this is not an actual part of the formalism.
Example 2. Consider a RSCFG $H=\left(G_{I}, G_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$, where $G_{I}=$ $\left(N_{I}, T_{I}, P_{I}, \mathrm{~S}_{I}\right), G_{O}=\left(N_{O}, T_{O}, P_{O}, \mathrm{~S}_{O}\right), N_{I}=\left\{\mathrm{S}_{I}\right.$, NP-SBJ, VP, PP-TMP, PP-DIR $\}, T_{I}=\{\mathrm{NP}, \mathrm{V}$, Det $\}, N_{O}=\left\{\mathrm{S}_{O}, \mathrm{NP}-\mathrm{SBJ}, \mathrm{VP}, \mathrm{PP}-\mathrm{TMP}, \mathrm{PP}-\mathrm{DIR}\right\}, T_{O}=\{\mathrm{NP}$, V, Aux, Det, Prep\},

```
\(P_{I}=\)
    \(\begin{aligned}\{1: & \mathrm{S}_{I} & \rightarrow \text { NP-SBJ VP } \\ 2: & \mathrm{NP}-\mathrm{SBJ} & \rightarrow \text { NP Det }\langle w a\rangle \\ 3: & \mathrm{VP} & \rightarrow \text { PP-TMP PP-DIR V }\end{aligned}\)
```


and $P_{O}=$

| \{ 1: | $\mathrm{S}_{O} \rightarrow$ NP-SBJ VP | 4: PP-TMP $\rightarrow$ NP |
| :---: | :---: | :---: |
|  | SBJ $\rightarrow$ NP | 4z: PP-TMP $\rightarrow \varepsilon$ |
| 3 : | VP $\rightarrow$ Aux V PP-DIR PP-TMP | 5: PP-DIR $\rightarrow \operatorname{Prep}\langle t o\rangle$ NP |
|  |  | 5z: PP-DIR $\rightarrow \varepsilon$ |

Strictly according to the definitions, synchronous grammars generate pairs of sentences. However, in practice, we usually have the input sentence in the source language, and we want to translate it into the target language. That is, we want to generate the corresponding output sentence. The translation can be divided into two steps. First, we parse the input sentence using the input grammar. In $G_{I}$, a derivation that generates the example sentence may proceed as follows:
$\mathrm{S}_{I} \Rightarrow \mathrm{NP}-\mathrm{SBJ} \mathrm{VP}[1] \Rightarrow \mathrm{NP}\langle$ Takeshi-san $\rangle \operatorname{Det}\langle w a\rangle \mathrm{VP}[2] \Rightarrow \mathrm{NP}\langle$ Takeshi-san $\rangle$ $\operatorname{Det}\langle w a\rangle$ PP-TMP PP-DIR V $\langle$ ikimasu $\rangle[3] \Rightarrow \mathrm{NP}\langle$ Takeshi-san $\rangle \operatorname{Det}\langle$ wa $\rangle \mathrm{NP}\langle$ raishuu $\rangle$ PP-DIR V $\langle$ ikimasu $\rangle[4] \Rightarrow \mathrm{NP}\langle$ Takeshi-san $\rangle \operatorname{Det}\langle w a\rangle \mathrm{NP}\langle$ raishuu $\rangle \mathrm{NP}\langle$ Oosaka $\rangle \operatorname{Det}\langle n i\rangle$ V〈ikimasu〉 [5]

We have applied rules denoted by labels 12345 , in that order. Next, we use the sequence obtained in the first step, and apply the corresponding rules in the output grammar. Then, the derivation in $G_{O}$ proceeds as follows:
$\mathrm{S}_{O} \Rightarrow$ NP-SBJ VP [1] $\Rightarrow \mathrm{NP}\langle$ Takeshi $\rangle$ VP $[2] \Rightarrow \mathrm{NP}\langle$ Takeshi $\rangle$ Aux $\langle$ is $\rangle \mathrm{V}\langle$ going $\rangle$ PP-TMP PP-DIR [3] $\Rightarrow \mathrm{NP}\langle$ Takeshi $\rangle$ Aux $\langle$ is $\rangle \mathrm{V}\langle$ going $\rangle$ PP-DIR NP $\langle$ next week $\rangle[4] \Rightarrow$ $\mathrm{NP}\langle$ Takeshi $\rangle$ Aux $\langle i s\rangle \mathrm{V}\langle$ going $\rangle \operatorname{Prep}\langle t o\rangle \mathrm{NP}\langle$ Osaka $\rangle \mathrm{NP}\langle$ next week $\rangle[5]$

Also note the rules $4 z$ and $5 z$, which can be used to erase PP-TMP and PP-DIR. This represents the fact that these constituents may be omitted.

Next, compare the following sentences in Japanese (left) and English.

| Watashi wa raishuu Oosaka ni ikimasu. | I am going to Osaka next week. |
| :--- | :--- |
| Anata wa raishuu Oosaka ni ikimasu. | You are going to Osaka next week. |
| Takeshi-san wa raishuu Oosaka ni ikimasu. | Takeshi is going to Osaka next week. |

In English, the form of the auxiliary verb to be depends on many grammatical categories such as tense, number, or, as shown in this example, person - am for first person (present tense, singular), are for second, and is for third. On the other hand, note that the verb in the Japanese sentences (ikimasu, long form of $i k u$ ) is always the same (out of the grammatical categories mentioned, only tense would affect inflection). If we want to
translate such sentence from Japanese to English, we need to choose the correct form of the verb. We can get the necessary information by looking at the subject.

Example 3. Consider a SMAT $H=\left(G_{I}, M_{I}, G_{O}, M_{O}, \Psi, \varphi_{I}, \varphi_{O}\right)$, where $G_{I}=$ $\left(N_{I}, T_{I}, P_{I}, \mathrm{~S}_{I}\right), G_{O}=\left(N_{O}, T_{O}, P_{O}, \mathrm{~S}_{O}\right), N_{I}=\left\{\mathrm{S}_{I}\right.$, NP-SBJ, VP, PP-TMP, PP-DIR $\}$, $T_{I}=\left\{\mathrm{NP}, \mathrm{NP}_{1}, \mathrm{NP}_{2}, \mathrm{NP}_{3}, \mathrm{~V}, \operatorname{Det}\right\}, N_{O}=\left\{\mathrm{S}_{O}, \mathrm{NP}-\mathrm{SBJ}, \mathrm{VP}, \mathrm{PP}-\mathrm{TMP}\right.$, PP-DIR, Aux $\left.{ }_{x}\right\}$, $T_{O}=\left\{\mathrm{NP}, \mathrm{NP}_{1}, \mathrm{NP}_{2}, \mathrm{NP}_{3}, \mathrm{~V}\right.$, Aux $_{1}$, Aux $_{2}$, Aux $_{3}$, Det, Prep $\}$, $P_{I}=$
$\left\{1: \quad \mathrm{S}_{I} \rightarrow\right.$ NP-SBJ VP
$2 a:$ NP-SBJ $\rightarrow \mathrm{NP}_{1} \operatorname{Det}\langle w a\rangle$
$2 b:$ NP-SBJ $\rightarrow \mathrm{NP}_{2} \operatorname{Det}\langle w a\rangle$
$2 c: ~ \mathrm{NP}-\mathrm{SBJ} \rightarrow \mathrm{NP}_{3} \operatorname{Det}\langle w a\rangle$
VP $\rightarrow$ PP-TMP PP-DIR V

$$
3: \quad \text { VP } \rightarrow \text { PP-TMP PP-DIR V }
$$

4: PP-TMP $\rightarrow$ NP
4z: PP-TMP $\rightarrow \varepsilon$
5: $\quad$ PP-DIR $\rightarrow$ NP $\operatorname{Det}\langle n i\rangle$
$5 z: \quad$ PP-DIR $\rightarrow \varepsilon$

$$
P_{O}=
$$

| 1: | $\mathrm{S}_{O} \rightarrow$ NP-SBJ VP | 4z: PP-TMP $\rightarrow \varepsilon$ |
| :---: | :---: | :---: |
|  | NP-SBJ $\rightarrow \mathrm{NP}_{1}$ | 5: PP-DIR $\rightarrow$ Prep $\langle t o\rangle$ NP |
|  | NP-SBJ $\rightarrow \mathrm{NP}_{2}$ | 5z: PP-DIR $\rightarrow \varepsilon$ |
|  | NP-SBJ $\rightarrow \mathrm{NP}_{3}$ | 6a: Aux $_{x} \rightarrow$ Aux $_{1}$ |
| 3 : | VP $\rightarrow$ Aux ${ }_{x}$ V PP-DIR PP-TMP | 6b: $\mathrm{Aux}_{x} \rightarrow \mathrm{Aux}_{2}$ |
|  | PP-TMP $\rightarrow$ NP | $6 c: \quad \operatorname{Aux}_{x} \rightarrow \mathrm{Aux}_{3}$ |

$M_{I}=\left\{m_{1}: 1, m_{2 a}: 2 a, m_{2 b}: 2 b, m_{2 c}: 2 c, m_{3}: 3, m_{4}: 4, m_{4 z}: 4 z, m_{5}: 5, m_{5 z}: 5 z\right\}$, and $M_{O}=\left\{m_{1}: 1, m_{2 a}: 2 a 6 a, m_{2 b}: 2 b 6 b, m_{2 c}: 2 c 6 c, m_{3}: 3, m_{4}: 4, m_{4 z}: 4 z\right.$, $\left.m_{5}: 5, m_{5 z}: 5 z\right\}$.

An example of a derivation follows.
$\mathrm{S}_{I} \Rightarrow$ NP-SBJ VP $\left[m_{1}\right] \Rightarrow$ NP-SBJ PP-TMP PP-DIR V $\langle$ ikimasu $\rangle\left[m_{3}\right] \Rightarrow$ $\mathrm{NP}_{1}\langle$ watashi $\rangle \operatorname{Det}\langle$ wa $\rangle$ PP-TMP PP-DIR V $\langle$ ikimasu $\rangle\left[m_{2 a}\right] \Rightarrow \mathrm{NP}_{1}\langle$ watashi $\rangle \operatorname{Det}\langle$ wa $\rangle$ $\mathrm{NP}\langle$ raishuu $\rangle$ PP-DIR V〈ikimasu $\rangle\left[m_{4}\right] \Rightarrow \mathrm{NP}_{1}\langle$ watashi $\rangle \operatorname{Det}\langle$ wa $\rangle \mathrm{NP}\langle$ raishuu $\rangle$ $\mathrm{NP}\langle$ Oosaka $\rangle \operatorname{Det}\langle n i\rangle \mathrm{V}\langle$ ikimasu $\rangle\left[m_{5}\right]$
$\mathrm{S}_{O} \Rightarrow$ NP-SBJ VP $\left[m_{1}\right] \Rightarrow$ NP-SBJ Aux ${ }_{x}\langle$ be $\rangle$ V $\langle$ going $\rangle$ PP-DIR PP-TMP $\left[m_{3}\right] \Rightarrow$ $\mathrm{NP}_{1}\langle I\rangle$ Aux $_{1}\langle a m\rangle$ V $\langle$ going $\rangle$ PP-DIR PP-TMP $\left[m_{2 a}\right] \Rightarrow \mathrm{NP}_{1}\langle I\rangle$ Aux $_{1}\langle a m\rangle \mathrm{V}\langle$ going $\rangle$ PP-DIR NP $\langle$ next week $\rangle\left[m_{4}\right] \Rightarrow \mathrm{NP}_{1}\langle I\rangle \mathrm{Aux}_{1}\langle$ am $\rangle \mathrm{V}\langle$ going $\rangle$ Prep $\langle$ to $\rangle \mathrm{NP}\langle$ Osaka $\rangle$ $\mathrm{NP}\langle$ next week $\rangle\left[m_{5}\right]$

Depending on person of the subject, we apply one of the matrices $m_{2 a}, m_{2 b}$, or $m_{2 c}$. In the input grammar (Japanese), these matrices contain only one rule, which involves the subject itself. The verb is unaffected. In the output grammar (English), the matrices contain two rules, which ensure agreement between the subject and the (auxiliary) verb.

Instead of SMAT, we could also use SSCG to the same effect, with scattered context rules such as $\left(\mathrm{NP}-\mathrm{SBJ}, \mathrm{Aux}_{x}\right) \rightarrow\left(\mathrm{NP}_{1}, \mathrm{Aux}_{1}\right)$.

Let us have a look at some other syntactic structures. For instance, to form a question in Japanese, we can simply take a statement and append the particle $k a$ at the end of the sentence. In English, we need to place the auxiliary verb in front of the subject. Compare the following sentences in Japanese (left) and English.

Takeshi-san wa raishuu Oosaka ni ikimasu ka. Is Takeshi going to Osaka next week? Takeshi-san wa raishuu doko ni ikimasu ka. Where is Takeshi going next week? Takeshi-san wa itsu Oosaka ni ikimasu ka. When is Takeshi going to Osaka?

Observe that in Japanese, the only difference between the three questions is the word Oosaka being replaced by doko (where), or raishuu by itsu (when). However, in English, the structure of the sentence changes further, as illustrated by the derivation trees in Figure 1. The interrogative pronoun (where, when) is taken from its "original" position and placed at the beginning of the sentence (this common principle known as wh-movement is present in many languages besides English).


Fig. 1. Derivation trees for Japanese and English question

To reflect this in our grammar, we can add nonterminal symbol PN-INT to $N_{O}$ and terminal symbol PN to both $T_{I}$ and $T_{O}$. To $P_{I}$, we add rules

$$
\begin{array}{ll}
1 q: \mathrm{S} \rightarrow \mathrm{NP}-\mathrm{SBJ} \text { VP } \operatorname{Det}\langle k a\rangle & 4 q: \mathrm{PP}-\mathrm{TMP} \rightarrow \mathrm{PN}\langle i t s u\rangle \\
& 5 q: \quad \mathrm{PP}-\mathrm{DIR} \rightarrow \mathrm{PN}\langle\text { doko }\rangle \operatorname{Det}\langle n i\rangle
\end{array}
$$

and to $P_{O}$, rules

$$
\begin{array}{rll}
1 q: & \mathrm{S} \rightarrow \text { Aux }_{x} \text { NP-SBJ VP } & 3 q: \quad \text { VP } \rightarrow \text { V PP-DIR PP-TMP } \\
1 q i: & \mathrm{S} \rightarrow \text { PN-INT Aux } x_{x} \text { NP-SBJ VP } & 7 q: \text { PN-INT } \rightarrow \text { PN }
\end{array}
$$

Finally, we add matrices $m_{1 q}, m_{1 q i}: 1 q 3, m_{4 q}: 4 q, m_{5 q}: 5 q$, to $M_{I}$ and $m_{1 q}: 1 q 3 q$, $m_{1 q i}: 1 q i 3 q, m_{4 q}: 7 q 4 z, m_{5 q}: 7 q 5 z$ to $M_{O}$ (recall that the rules $4 z$ and $5 z$ erase PPTMP and PP-DIR, respectively).

An example of a derivation follows.
$\mathrm{S}_{I} \Rightarrow$ NP-SBJ PP-TMP PP-DIR V $\langle$ ikimasu $\rangle \operatorname{Det}\langle k a\rangle\left[m_{1 q i}\right] \Rightarrow \mathrm{NP}_{3}\langle$ Takeshi-san $\rangle$ $\operatorname{Det}\langle w a\rangle$ PP-TMP PP-DIR V $\langle$ ikimasu $\rangle \operatorname{Det}\langle k a\rangle\left[m_{2 c}\right] \Rightarrow \mathrm{NP}_{3}\langle$ Takeshi-san $\rangle \operatorname{Det}\langle w a\rangle$ $\mathrm{NP}\langle$ raishuu $\rangle$ PP-DIR V $\langle$ ikimasu $\rangle \operatorname{Det}\langle k a\rangle\left[m_{4}\right] \Rightarrow \mathrm{NP}_{3}\langle$ Takeshi-san $\rangle \operatorname{Det}\langle$ wa $\rangle$ $\mathrm{NP}\langle$ raishuu $\rangle \mathrm{PN}\langle$ doko $\rangle \operatorname{Det}\langle n i\rangle \mathrm{V}\langle$ ikimasu $\rangle \operatorname{Det}\langle k a\rangle\left[m_{5 q}\right]$
$\mathrm{S}_{O} \Rightarrow \mathrm{PN}-\mathrm{INT} \mathrm{Aux}_{x}\langle b e\rangle$ NP-SBJ V $\langle$ going $\rangle$ PP-DIR PP-TMP $\left[m_{1 q i}\right] \Rightarrow$ PN-INT Aux ${ }_{3}\langle i s\rangle \mathrm{NP}_{3}\langle$ Takeshi $\rangle \mathrm{V}\langle$ going $\rangle$ PP-DIR PP-TMP $\left[m_{2 c}\right] \Rightarrow$ PN-INT Aux $_{3}\langle$ is $\rangle \mathrm{NP}_{3}\langle$ Takeshi $\rangle \mathrm{V}\langle$ going $\rangle$ PP-DIR NP $\langle$ next week $\rangle\left[m_{4}\right] \Rightarrow \mathrm{PN}\langle$ where $\rangle$ Aux ${ }_{3}\langle$ is $\rangle$ $\mathrm{NP}_{3}\langle$ Takeshi $\rangle \mathrm{V}\langle$ going $\rangle \mathrm{NP}\langle$ next week $\rangle\left[m_{5 q}\right.$ ]

Note that the matrices ensuring subject-verb agreement (see Example 3) work without any changes for all of the structures discussed above. Clearly, it is possible to capture the relation within a purely context-free framework as well. However, the necessary grammatical information would have to be propagated through the derivation tree. This means that we would have to add separate rules covering all possibilities (person, number. ..) for each of the structures, even though the structures themselves are not actually affected.

Using SMAT or SSCG, we are able to describe the relation more easily, with only a relatively small number of rules. The presented example is somewhat special, as to be is an irregular verb. In English, we usually only need to distinguish two cases: third person singular and other. In languages with rich inflection, such as Czech (see [5]), this advantage becomes even more important.

## 6. Conclusion

In this paper, we have discussed the generative power of synchronous grammars based on linked rules. To summarize the main results, we have obtained the following hierarchy of the studied language classes:

$$
C F \subset \mathscr{L}(R S C F G)=\mathscr{L}(M A T)=\mathscr{L}(S M A T) \subset \mathscr{L}(S S C G)=R E
$$

Further research prospects in this direction include study of the properties of synchronous grammars with additional restrictions, such as left-most derivation, or propagating scattered context grammars. We can also consider synchronization of other wellknown formal models, using the same principle.

From the more practical point of view, we have presented models that can be used in natural language translation. We have demonstrated the basic principles on examples dealing with Japanese-English translation. We have shown that the extension beyond CFG allows us to describe some grammatical structures and transformations much more easily.

It is important to note that in our examples, we have made several assumptions. For example, we already have the sentence analyzed at low level, meaning that we can discern the individual words and have some basic grammatical information about them. For practical applications in machine translation, a more complex system is needed, incorporating other components such as a part-of-speech tagger and a dictionary to translate the actual meanings of the words. The component based on the discussed formal tools can be used to transform syntactic structures. Recently, many translation systems that use syntactic information have been developed (see [2], [7]). Such approaches are usually called syntax augmented, syntax-aided, or syntax based translation.

Another possible direction of further research is syntax analysis. In practice, we need to be able to parse the input sentence efficiently. While there are many well-known parsing algorithms for CFGs (such as CKY), matrix grammars and SCGs still present an open problem.

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[^0]:    ${ }^{1}$ This removes all terminals from the right-hand side of the rule. Note that if we left the rule unchanged, we would obtain the concatenation of the input and the output sentence. Further, if we wanted $L\left(H^{\prime}\right)=$ $L_{O}(H)$, we would simply modify $p_{I}$ instead of $p_{O}$.

[^1]:    ${ }^{2}$ Again, this removes all terminals from the right-hand side of the rules (see Theorem 1 ). $m[j]$ denotes the $j$-th rule in matrix $m$.

